

7. Principles of Phase Doppler Anemometry

Dantec Measurement Technology

<http://www.dantecmt.com>

General features of PDA

- **Extension of the LDA principle**
- **Simultaneous measurement of velocity (up to 3 components) and size of spherical particles as well as mass flux, concentration etc.**
- **First publication by Durst and Zaré in 1975**
- **First commercial instrument in 1984**
- **Non-intrusive measurement (optical technique), on-line and in-situ**
- **Absolute measurement technique (no calibration required)**
- **Very high accuracy**
- **Very high spatial resolution (small measurement volume)**

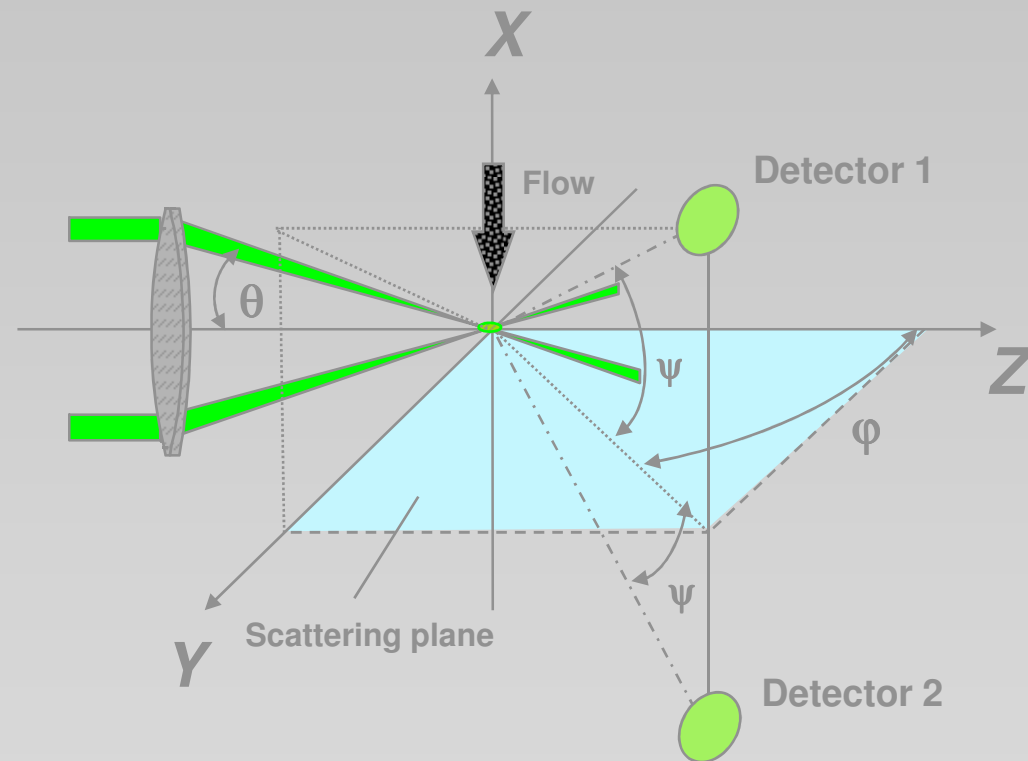
Preconditions for the application of PDA

- **Optical access to the measurement area (usually from two directions)**
- **Sphericity of particles (droplets, bubbles, solids)**
- **Homogeneity of particle medium**
(slight inhomogeneities may be tolerated if the concentration of the inhomogeneities is low and if the size of the inhomogeneities is much smaller than the wavelength used)
- **Refractive indices of the particle and the continuous medium must usually be known**
- **Particle size between ca. 0.5 μm and several millimeters**
- **Max. particle number concentration is limited**

Principle setup of PDA

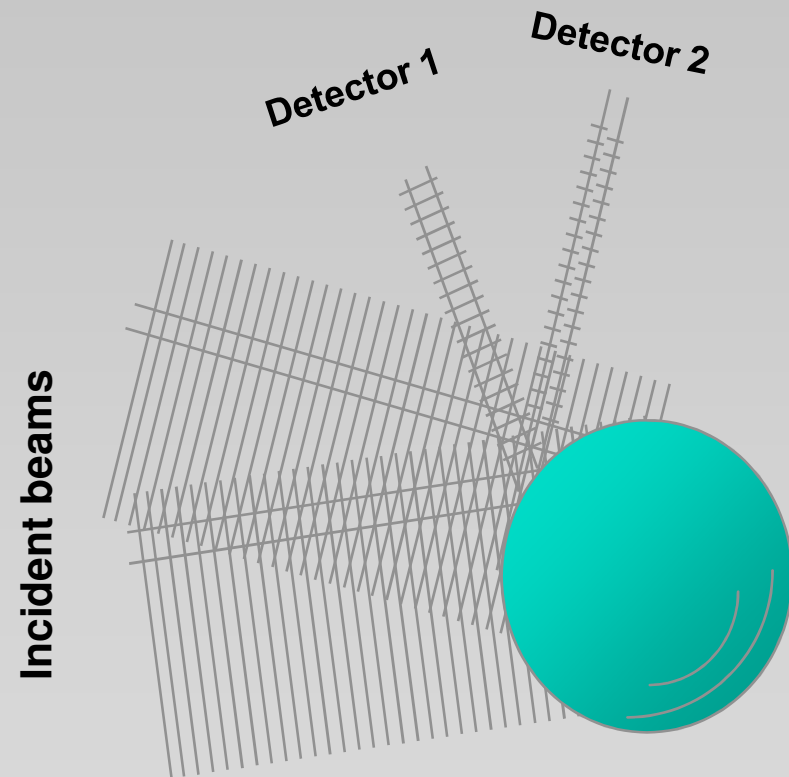
Optical parameters of a PDA setup:

- Beam intersection angle θ
- Scattering angle φ
- Elevation angle ψ
- Polarization (parallel or perpendicular to scattering plane)
- Shape and size of detector aperture



Optical principle of PDA

- A particle scatters light from two incident laser beams
- Both scattered waves interfere in space and create a beat signal with a frequency which is proportional to the velocity of the particle
- Two detectors receive this signal with different phases
- The phase shift between these two signals is proportional to the diameter of the particle



Phase relationships

The phase shift between two detectors is:

For reflection:

$$\Phi = \frac{2\pi d_p}{\lambda} \frac{\sin \theta \sin \psi}{\sqrt{2(1 - \cos \theta \cos \psi \cos \phi)}}$$

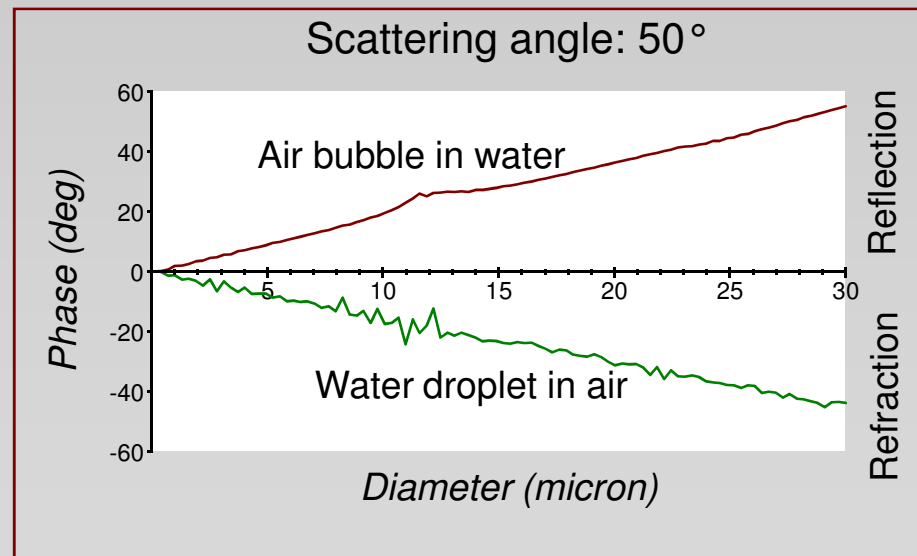
For 1st order refraction:

$$\Phi = \frac{-2\pi d_p}{\lambda} \frac{n_{rel} \sin \theta \sin \psi}{\sqrt{2(1 + \cos \theta \cos \psi \cos \phi)} (1 + n_{rel}^2 - n_{rel} \sqrt{2(1 + \cos \theta \cos \psi \cos \phi)}}$$

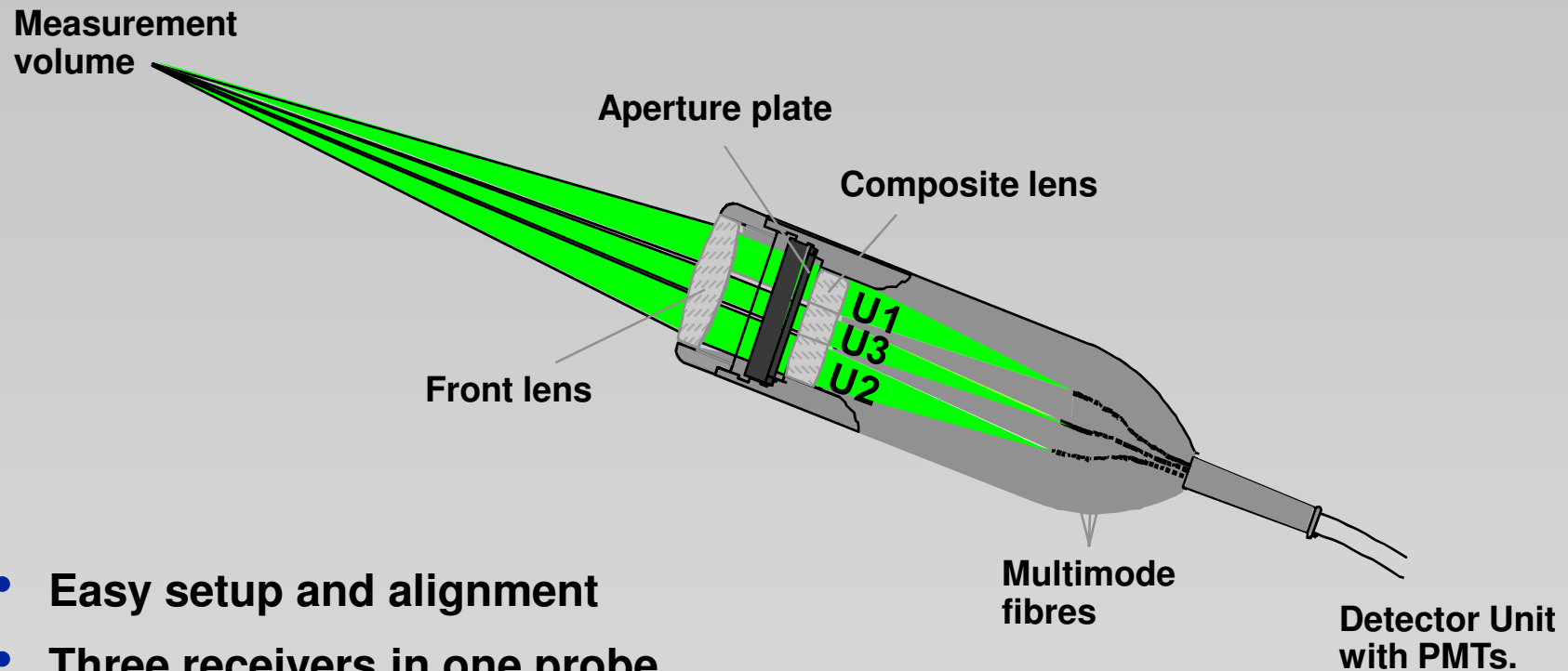
No calibration constant is contained in these equations.

Phase - diameter linearity

- A linear relationship between measured phase difference and particle diameter only exists, if the detector is positioned such that one light scattering mode dominates.
- Simultaneous detection of different scattering modes of comparable intensity leads to non-linearities in the phase-diameter relationship.



Dantec 57X40 FiberPDA



- Easy setup and alignment
- Three receivers in one probe
- Exchangeable aperture masks
- Up to three velocity components

Applications

- **Sprays and liquid atomization processes**
 - Water sprays
 - Fuel-, diesel injection
 - Paint coating
 - Agricultural sprays
 - Medical, pharmaceutical sprays
 - Cosmetic sprays
- **Powder production**
 - Spray drying
 - Liquid metal atomization
- **Bubble dynamics**
 - Cavitation
 - Aeration
 - Multiphase mass transfer

Automotive Fuel Injection

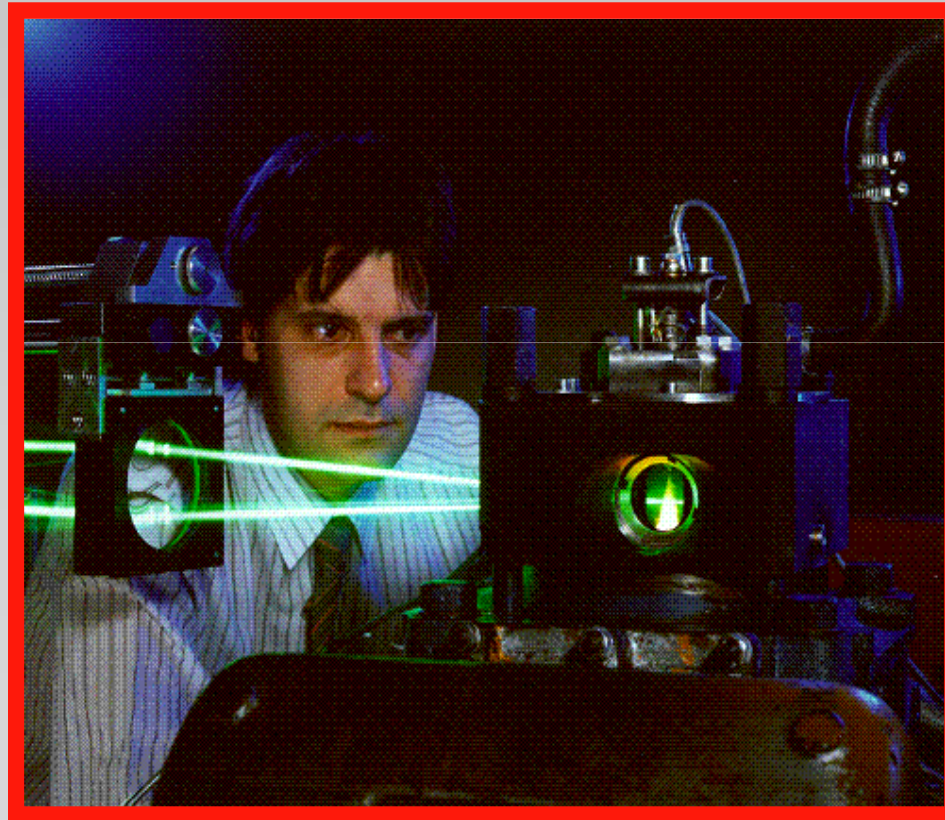


Photo: AVL, Graz, Austria

Nozzle Design

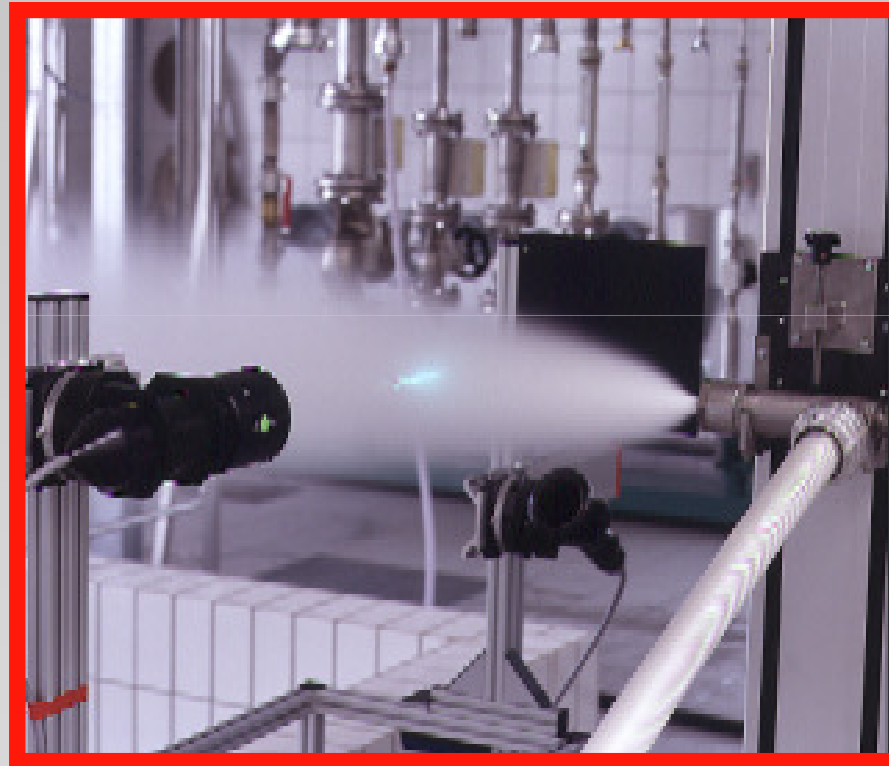


Photo: Gustav Schlick GmbH & Co., Untersiema, Germany

Aircraft Engine Fuel Injection

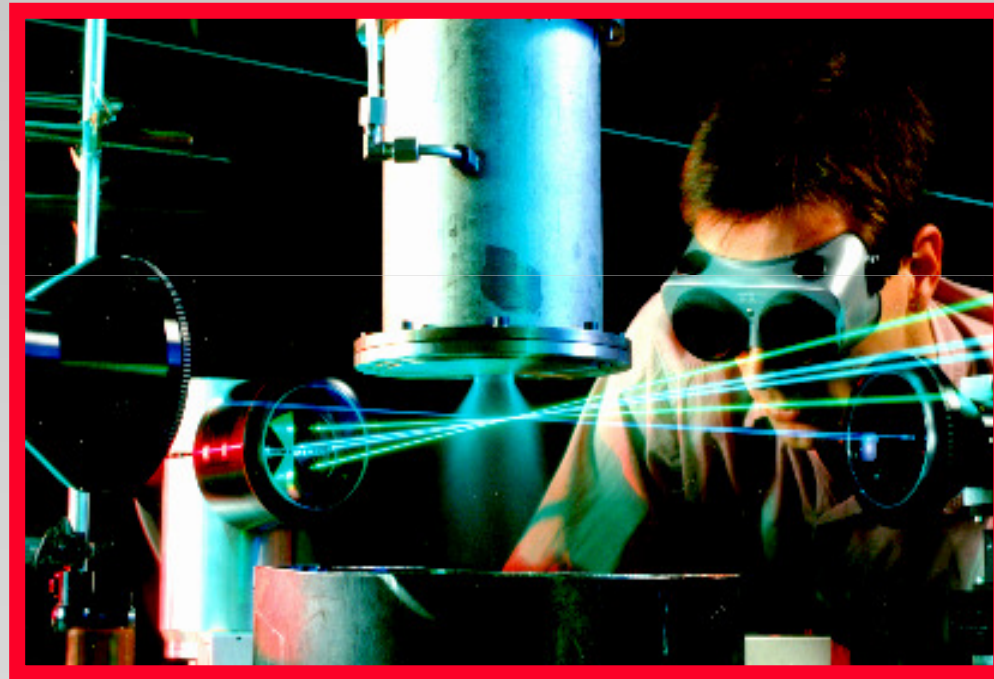
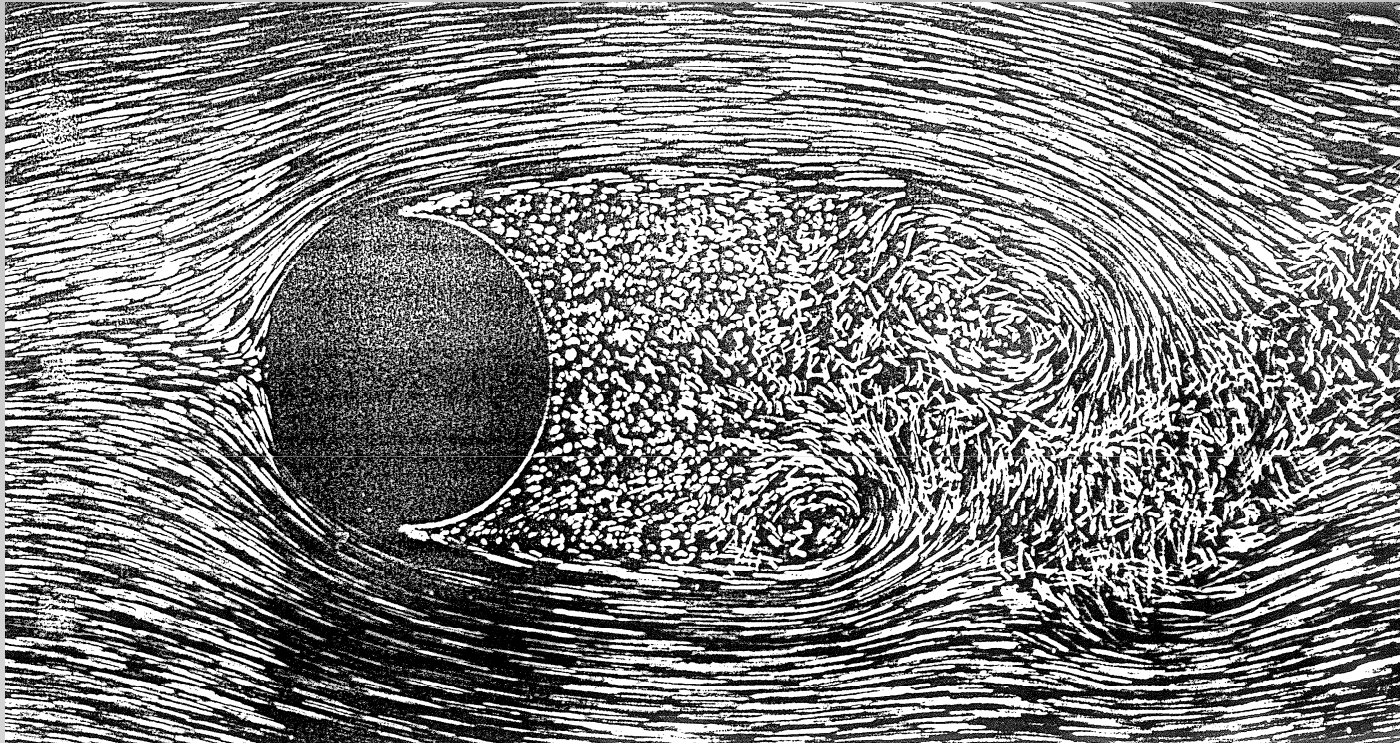
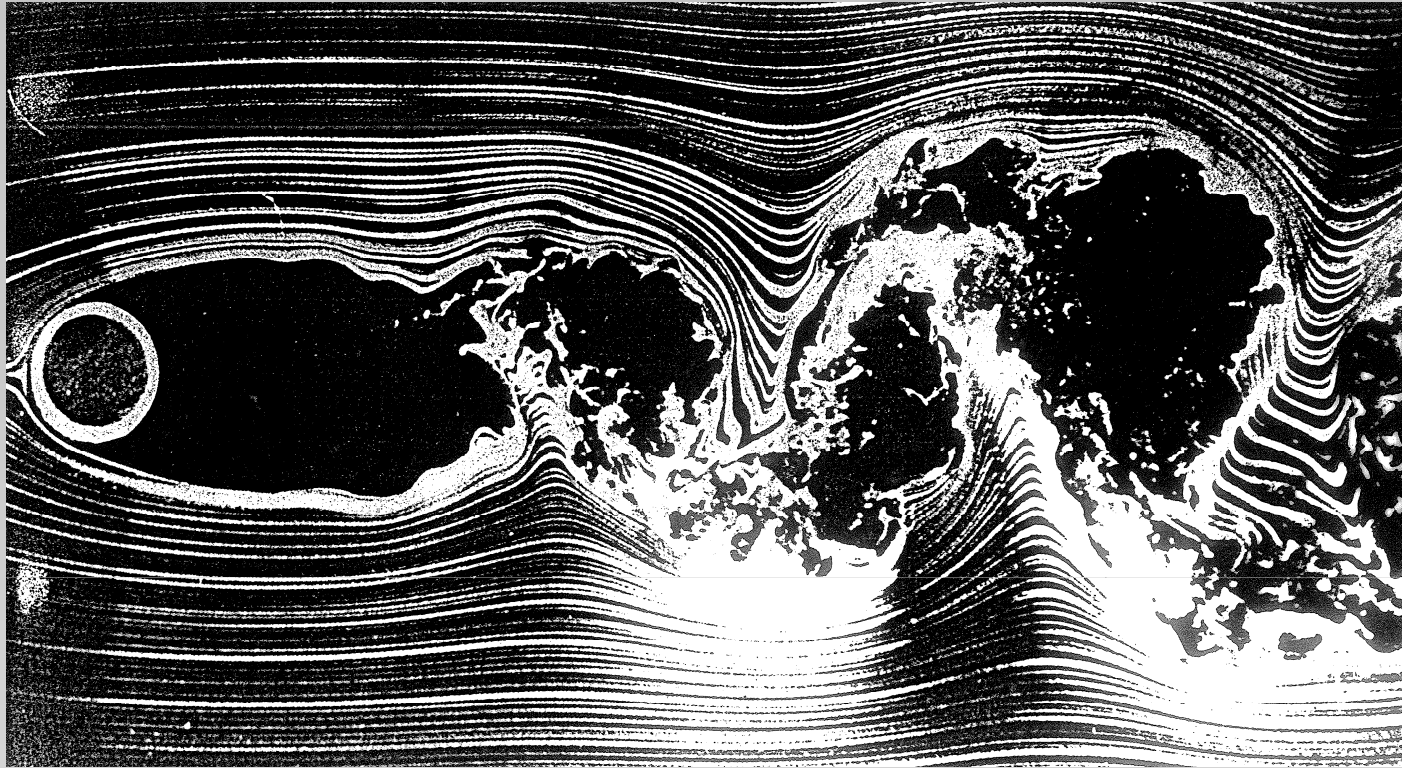


Photo: DLR, Institut für Antriebstechnik, Köln, Germany

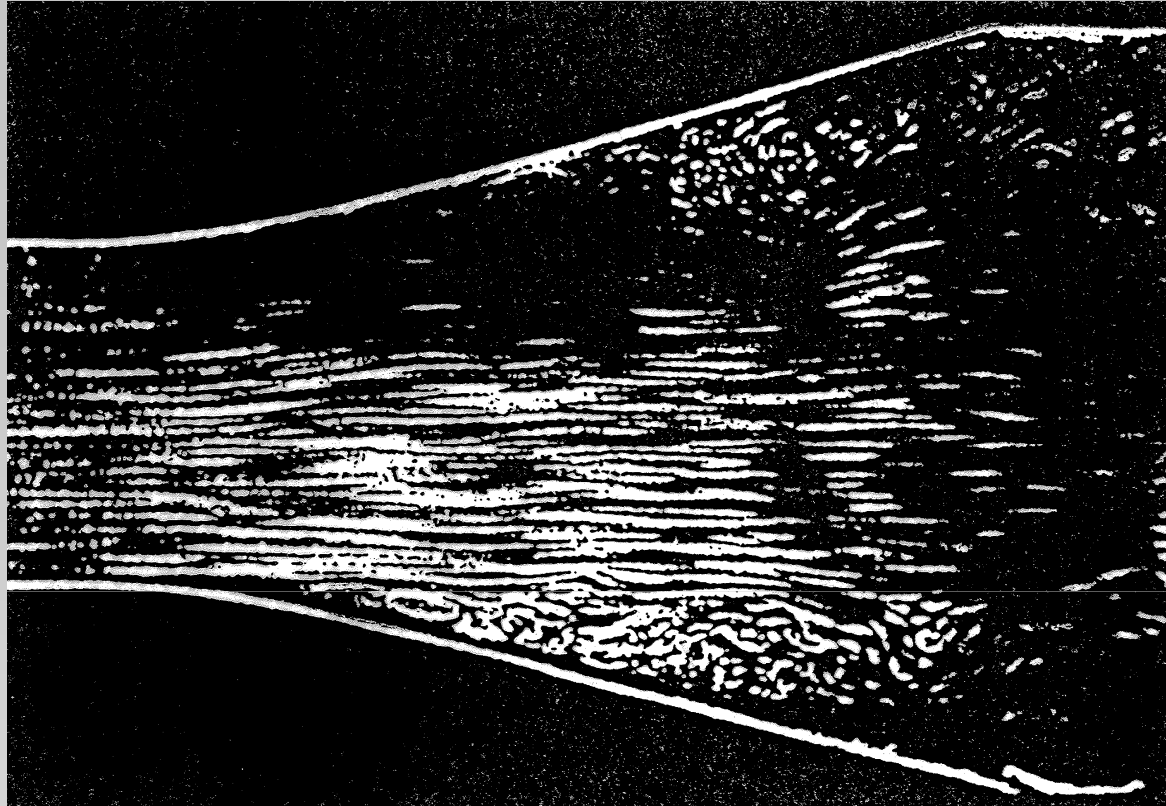
9. Light sheet flow visualisation



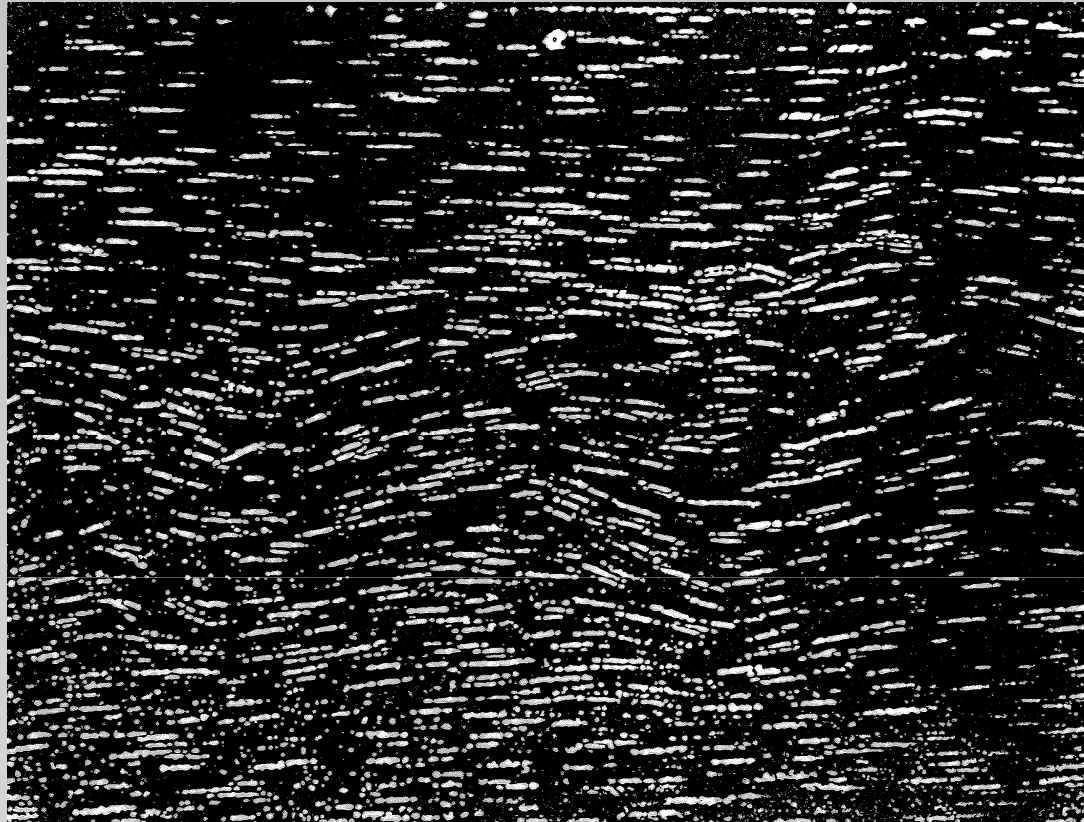
Flow visualised in the vicinity of a cylinder. $Re = 2\,000$. Air bubbles in water. (Van Dyke: An Album of Fluid Motion, Parabolic Press, Stanford, California, 1982)



Flow visualised in the vicinity of a cylinder. $Re = 10\ 000$.
Hydrogene bubbles in water. (Van Dyke: An Album of Fluid
Motion, Parabolic Press, Stanford, California, 1982)

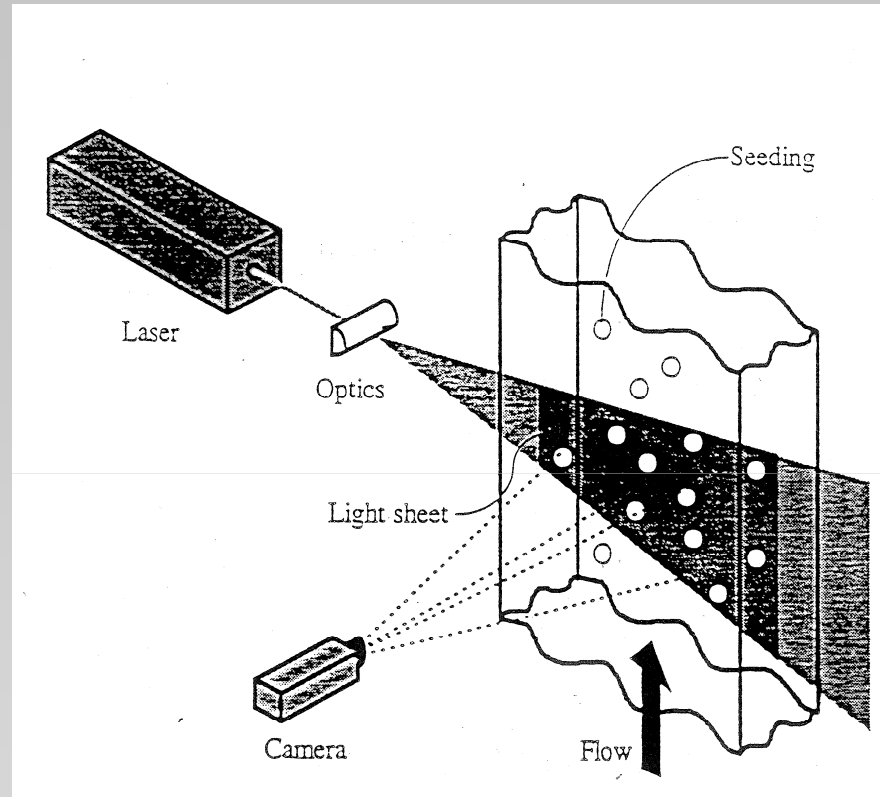


Flow visualised in a diffuser. Air bubbles in water. (Kaufmann, W.: Technische Hydro- und Aeromechanik, Springer Verlag, 1963)

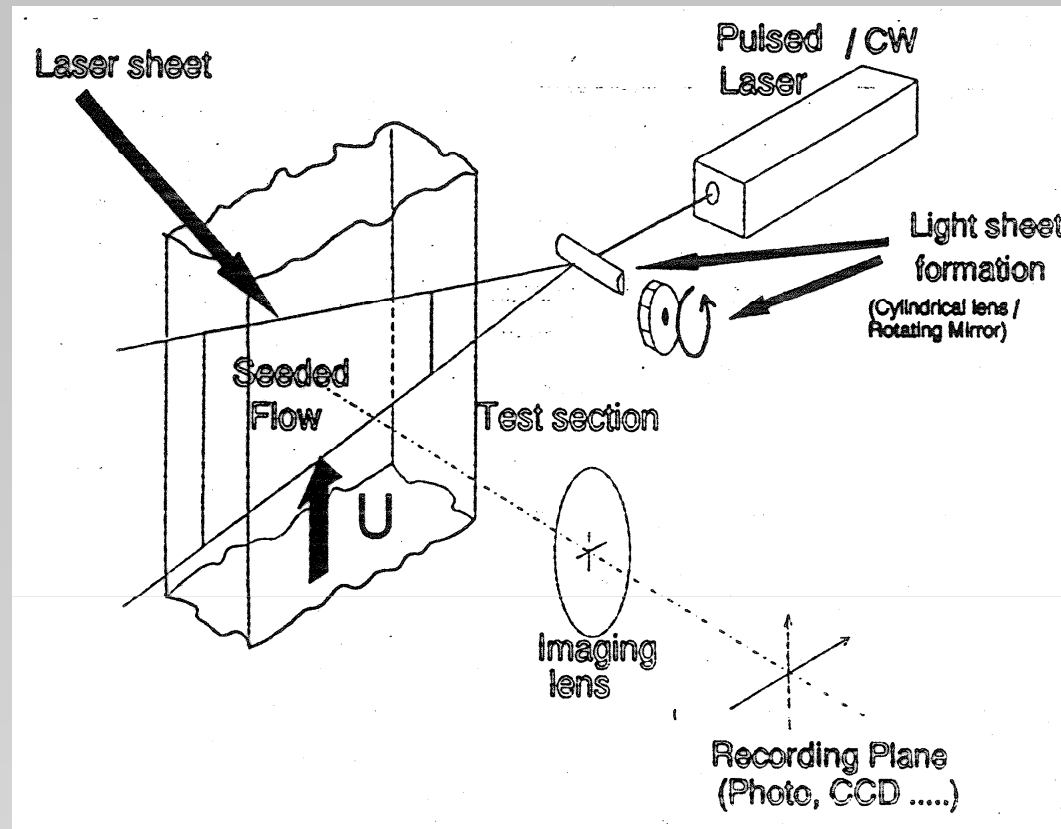


Particle Tracking Velocimetry. Flow downstream of a cylinder.
(Agui, J. C. A., Jimenez, J.: On the Performance of Particle
Tracking. J Fluid Mechanics, pp. 447 – 468, 1987)

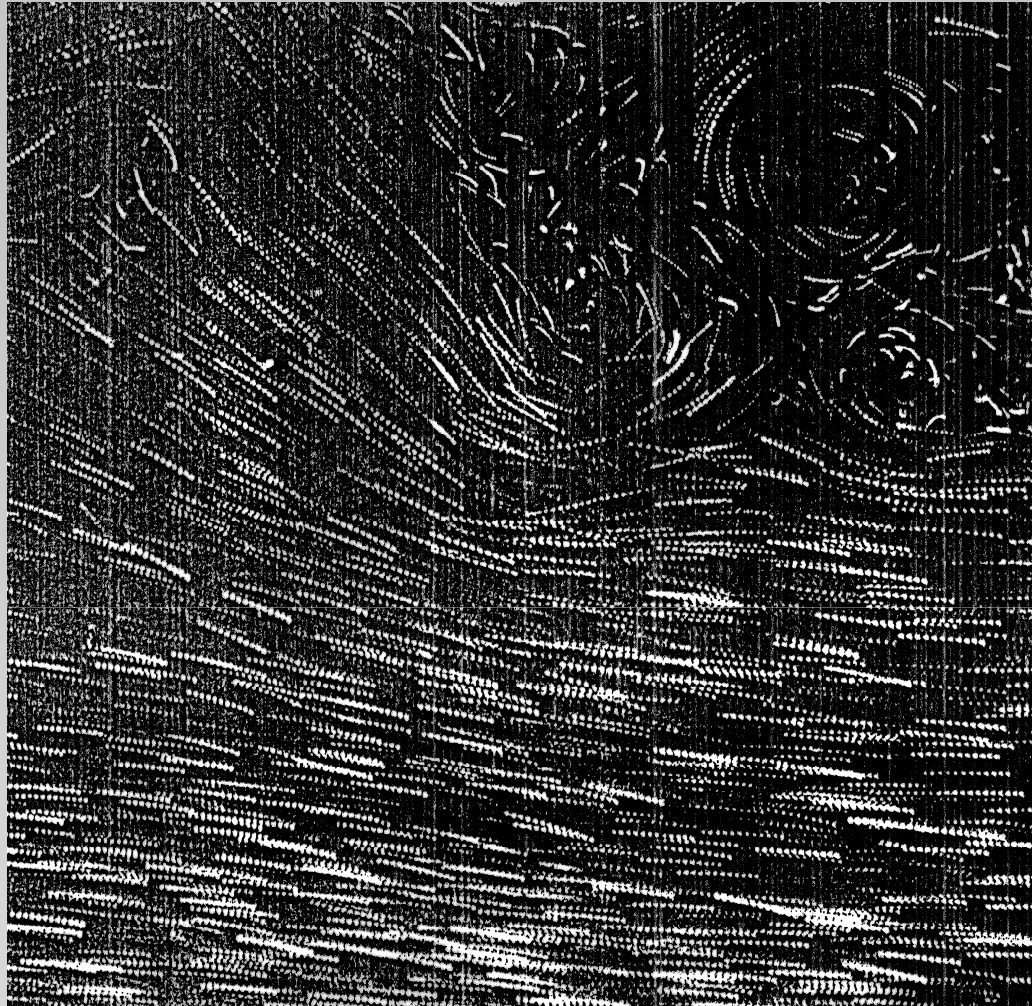
10. Particle Image Velocimetry (PIV)



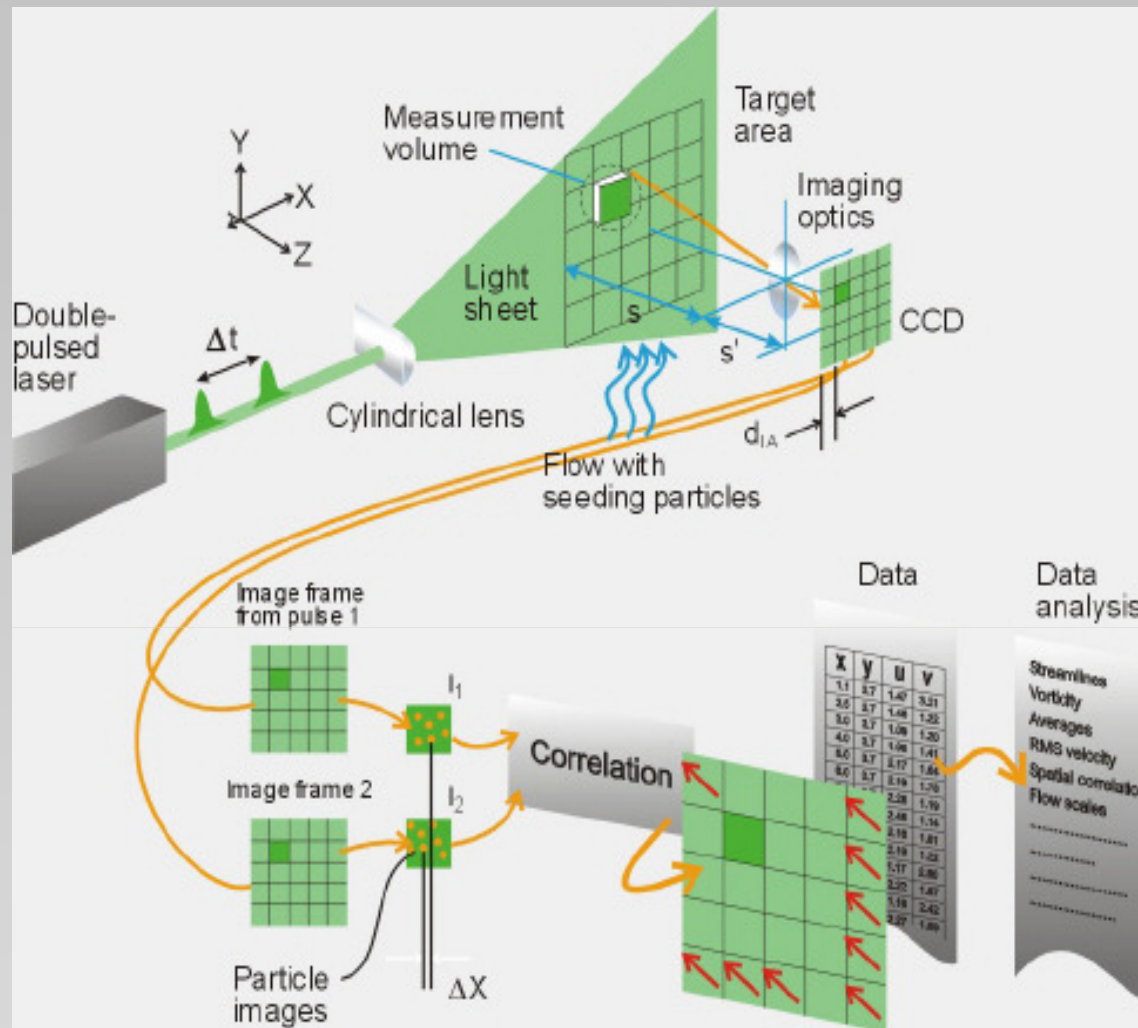
Principle of PIV (Lecture note by Pap, E., Otto-Von-Guericke Universitaet Magdeburg, Institut für Strömungstechnik und Thermodynamik, Lehrstuhl für Strömungsmaschinen)



PIV arrangement with rotating mirror laser sheet generator (Lecture note by Pap, E., Otto-Von-Guericke Universitaet Magdeburg, Institut für Strömungstechnik und Thermodynamik, Lehrstuhl für Strömungsmaschinen)



Typical image originated from multipulse illumination



Summary of PIV <http://www.dantecdynamics.com/piv/princip/index.html>

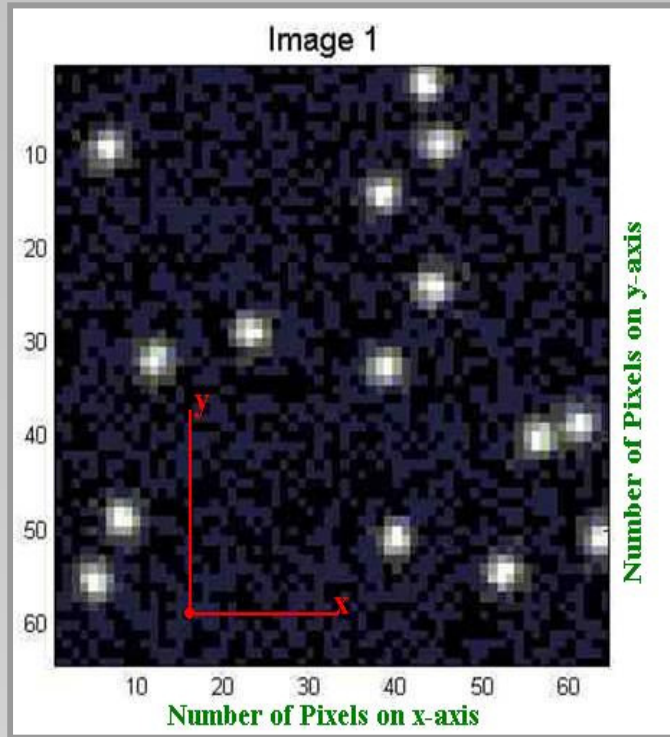


Image 1 at time t1

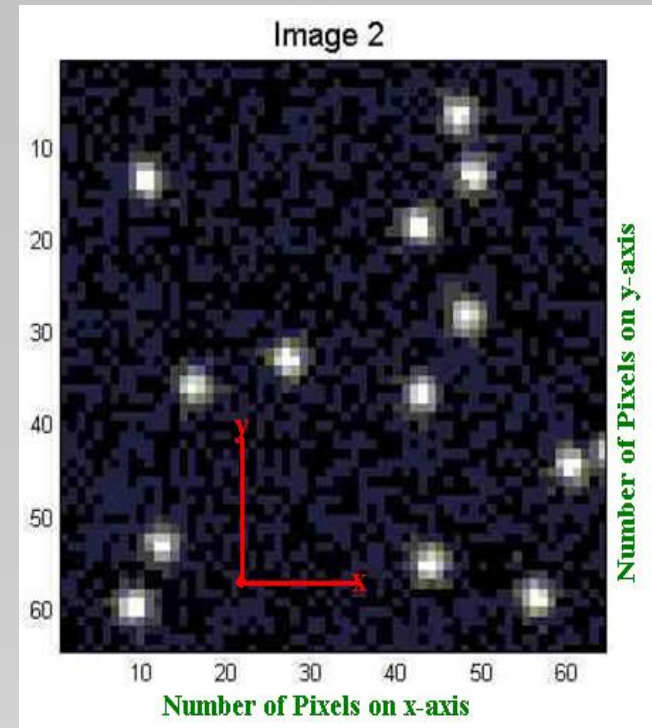
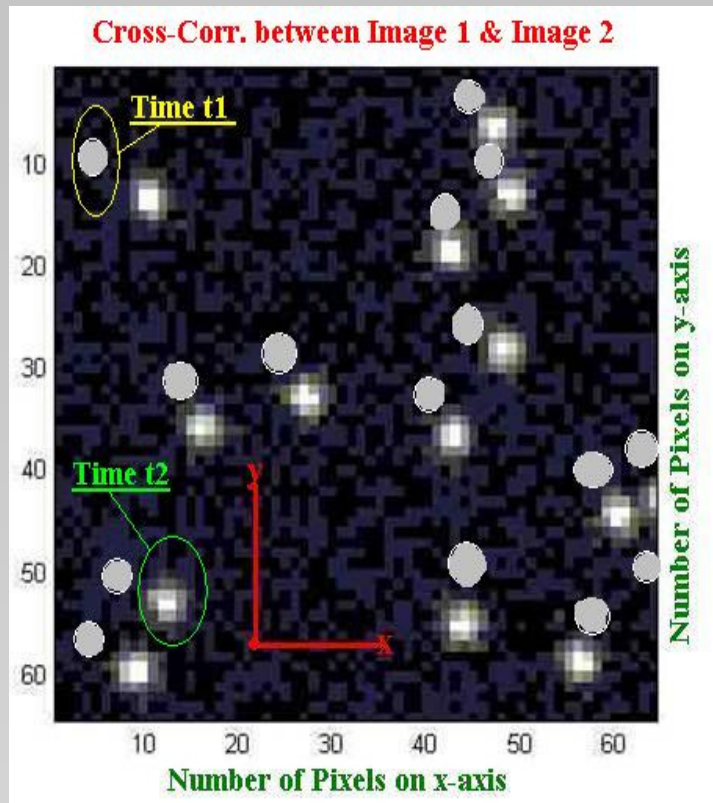


Image 2 at time t2

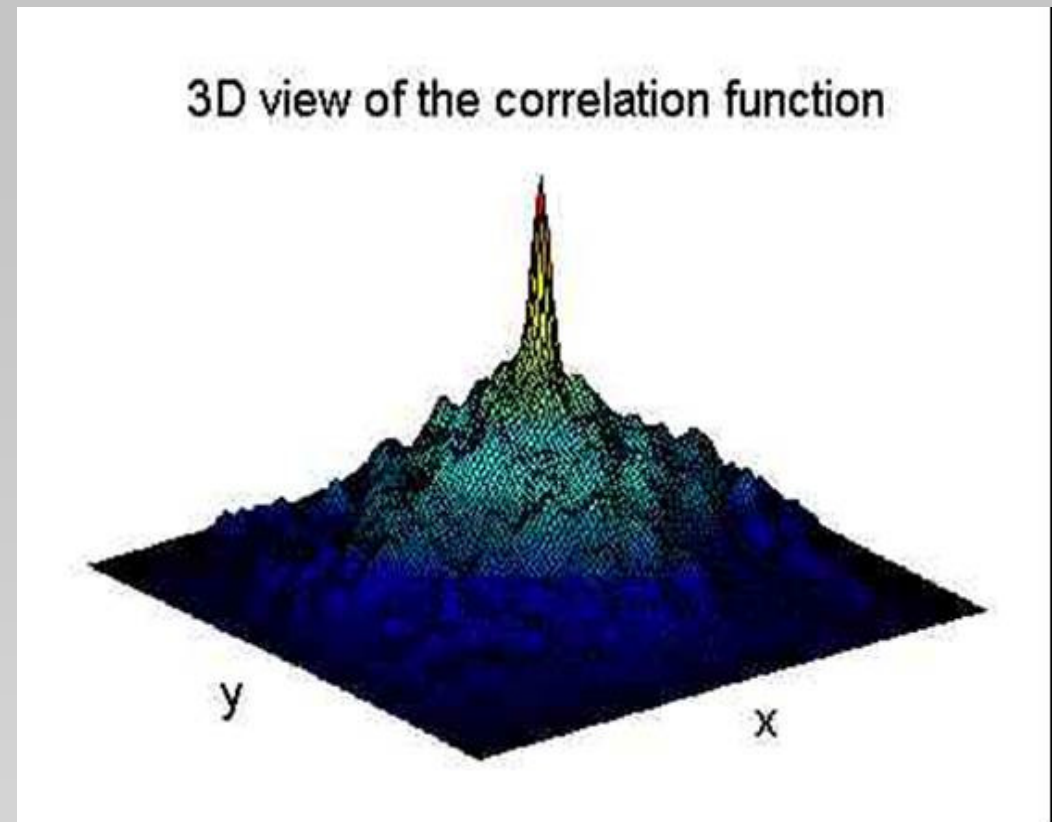
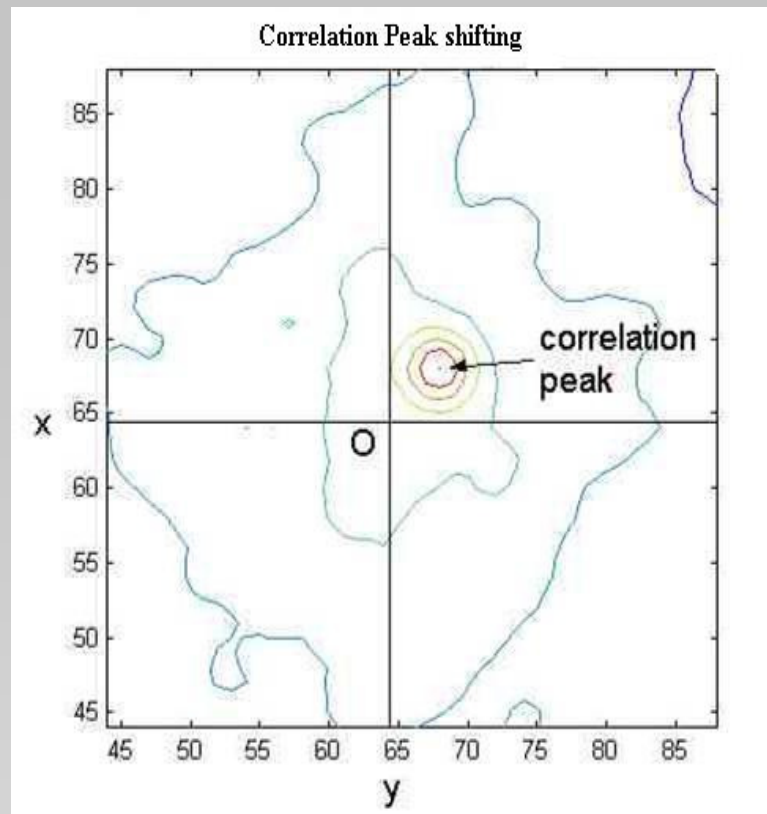
$$\bar{V} = \frac{\bar{\Delta x}}{\Delta t}$$

$$\bar{\Delta x} = ?$$

PIV Lecture_Notes, "Particle Image Velocimetry", University of WARWICK, Optical Engineering Laboratory (OEL)

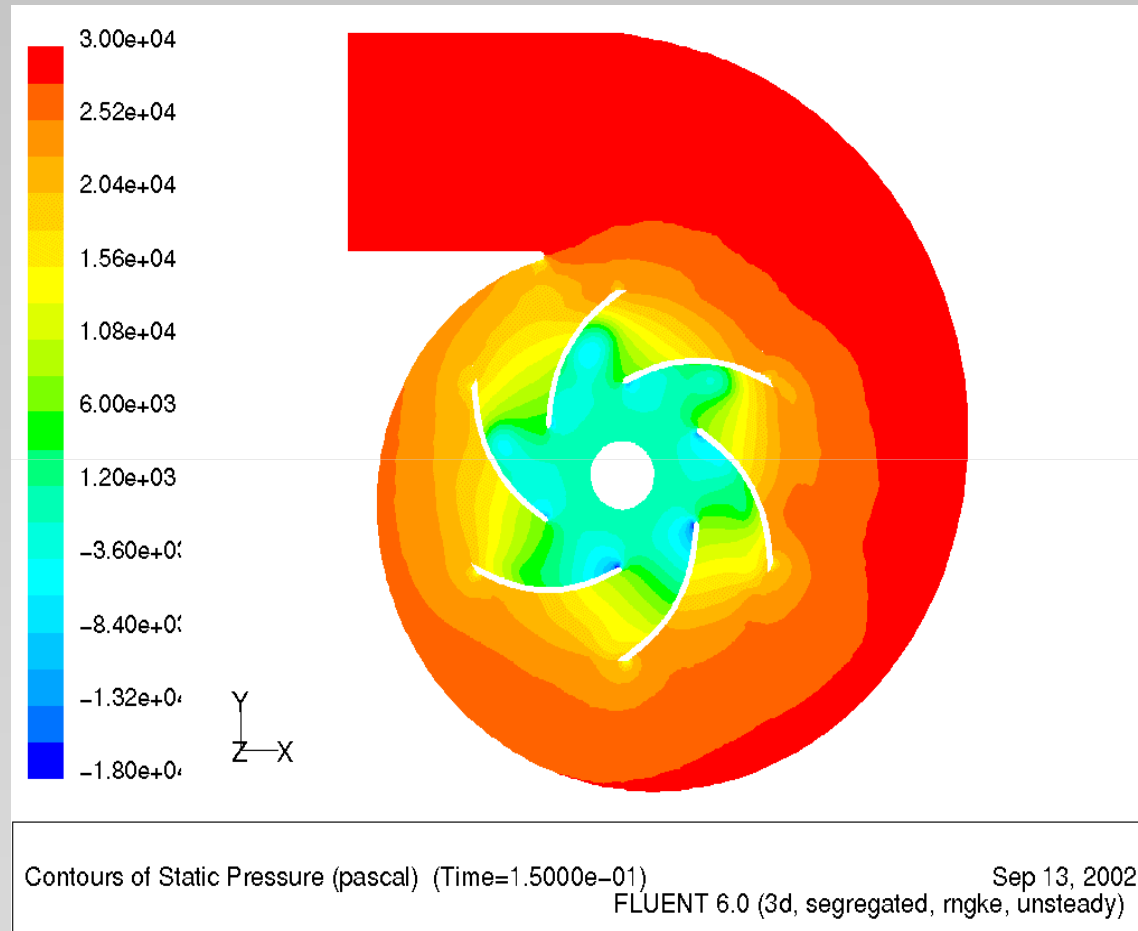


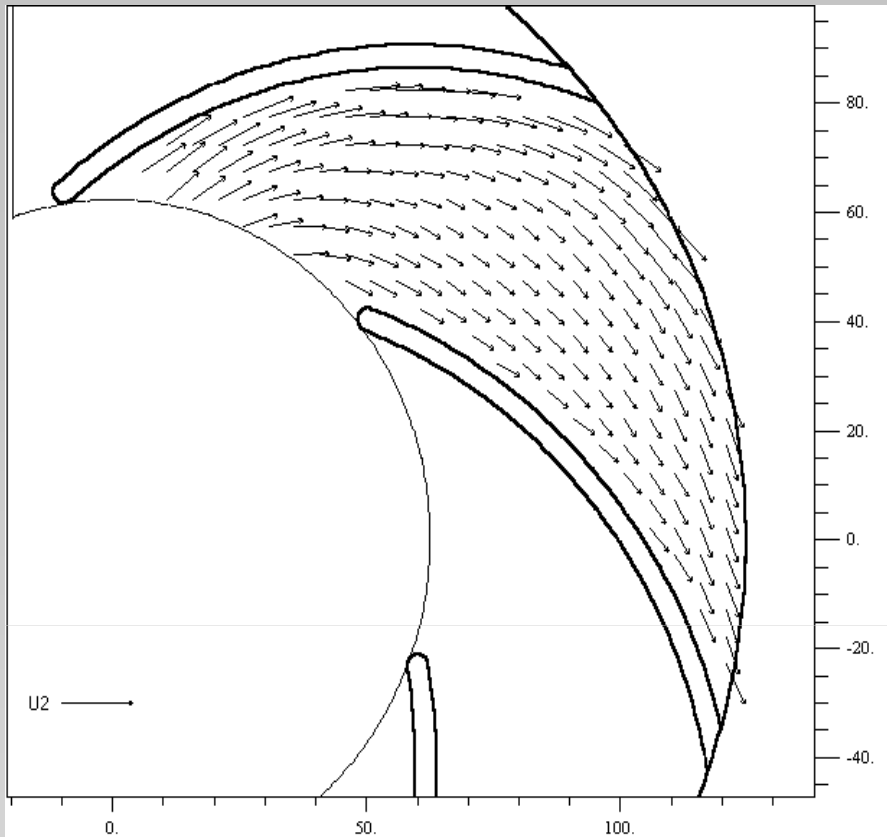
Maximum cross-correlation between Image 1 & Image 2



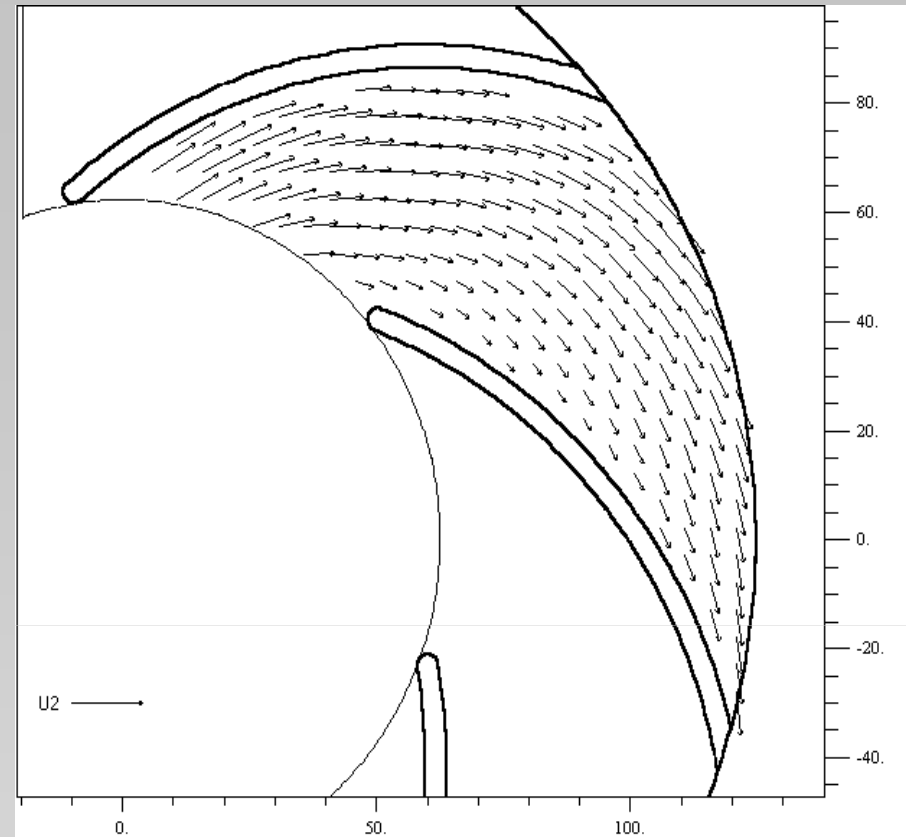
PIV Lecture_Notes, "Particle Image Velocimetry", University of WARWICK, Optical Engineering Laboratory (OEL)

Radial pump simulation: comparison of simulated flow field and PIV data





PIV measurement
(Otto-Von-Guericke
Universitaet Magdeburg)

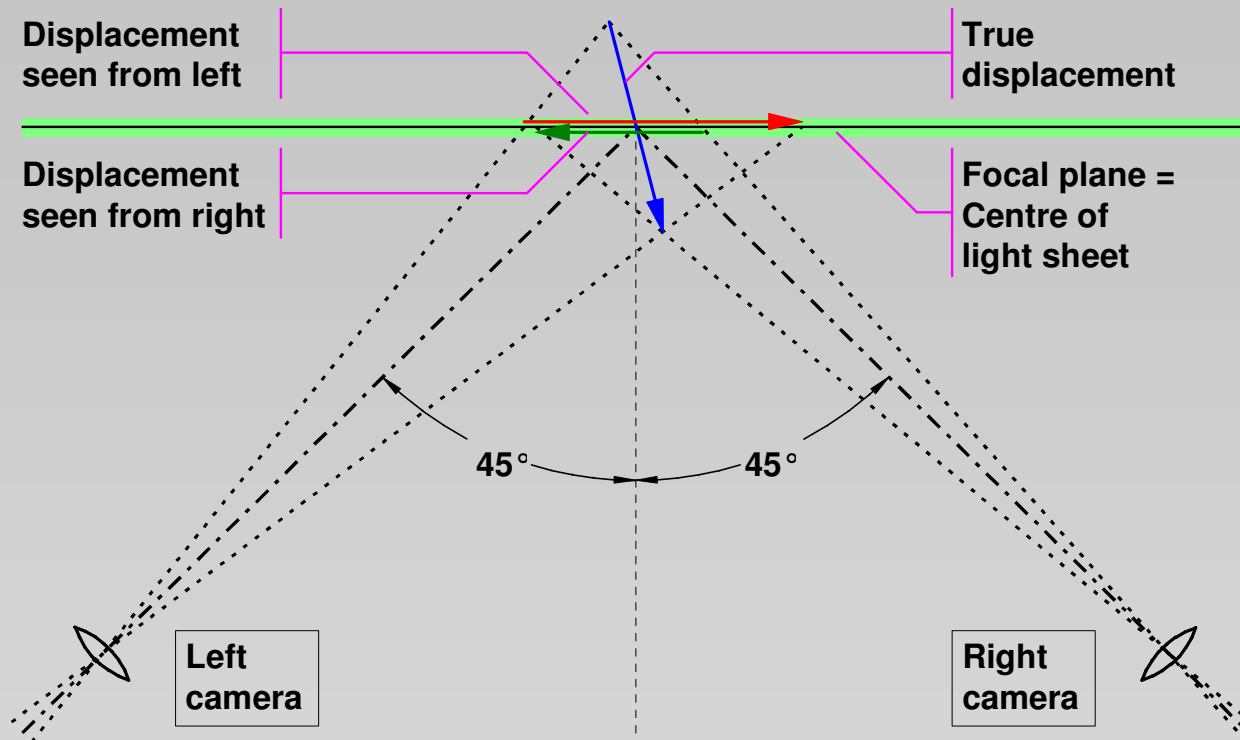


FLUENT simulation
(Dept. of Fluid Mechanics, BME)

FlowManager 3D-PIV (Stereo PIV)

- Theory of stereoscopic PIV
- Dantec 3D-PIV software
- Application example:
3D-PIV in an automotive wind tunnel
(used as example through the slide show)

Fundamentals of stereo vision



True 3D displacement ($\Delta X, \Delta Y, \Delta Z$) is estimated from a pair of 2D displacements ($\Delta x, \Delta y$) as seen from left and right camera respectively

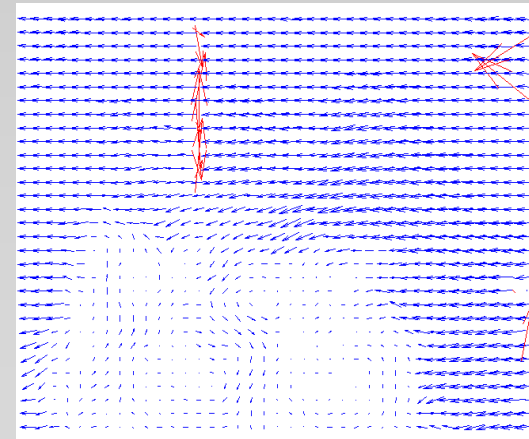
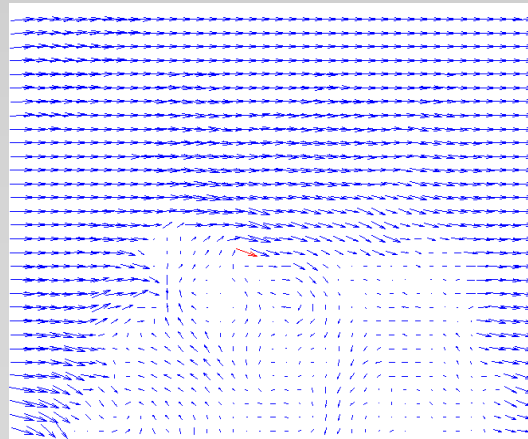
Left / Right 2D vector maps

Left & Right camera images are recorded simultaneously.

Conventional PIV processing produce 2D vector maps representing the flow field as seen from left & right.

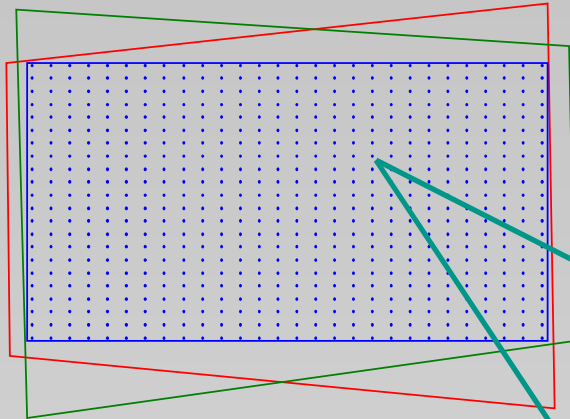
The vector maps are re-sampled in points corresponding to the interrogation grid.

Combining left / right results, 3D velocities are estimated.

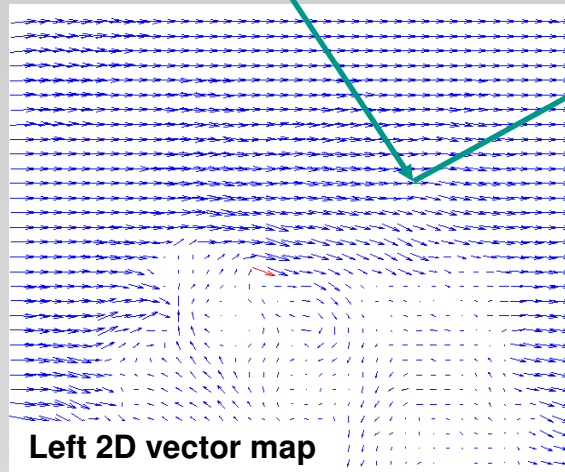
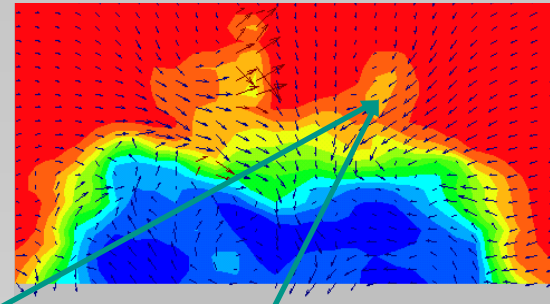


3D reconstruction

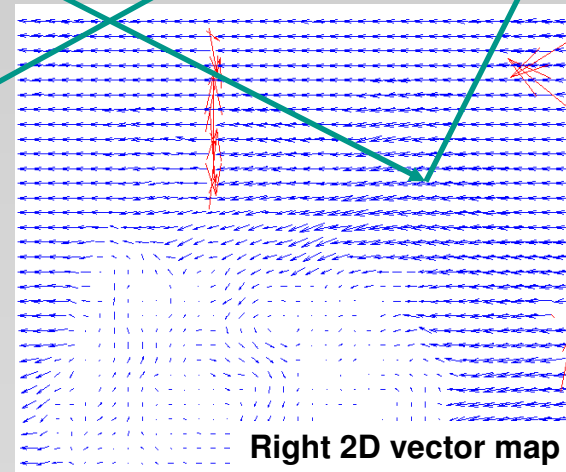
Overlap area with
interrogation grid



Resulting 3D vector map



Left 2D vector map



Right 2D vector map