

Advanced FLUENT Training UDF Mar 2007	Fluent User Services Center www.fluentusers.com	ANSYS [®] FLUENT [®]
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Welcome to Fluent Europe

- ◆ Introducing your trainer....
- ◆ Domestic issues:
 - Toilets – *all in entrance lobby near reception*
 - Tea, Coffee and Water – *help yourself, in customer dining room*
 - Fire Alarm and Escape Routes (*note alarms are tested at 09:15 Tuesday*)
 - Visitors Badge – *Leave on front reception desk if you go out at lunchtime, and when you leave for the evening.*
 - Smoking – *Outside only.*
 - Taxis – *Please let reception know by lunchtime if you need a taxi for the evening.*



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The slide is a presentation slide for the 'Welcome to Fluent Europe' training. It has a blue header bar with three sections: 'Advanced FLUENT Training UDF Mar 2007', 'Fluent User Services Center www.fluentusers.com', and the 'ANSYS FLUENT' logo. The main content area is white with a black border. It contains a title 'Welcome to Fluent Europe' and a list of items. The first item is 'Introducing your trainer....'. The second item is 'Domestic issues:', followed by a bulleted list of seven items, each with a red dot and italicized text. The last item is 'Taxis – Please let reception know by lunchtime if you need a taxi for the evening.' To the right of the list is a photograph of a modern, multi-story building with a glass facade and a red car parked in front. The footer of the slide is a blue bar with copyright information, the slide number '1-2', and 'ANSYS, Inc. Proprietary'.

Agenda

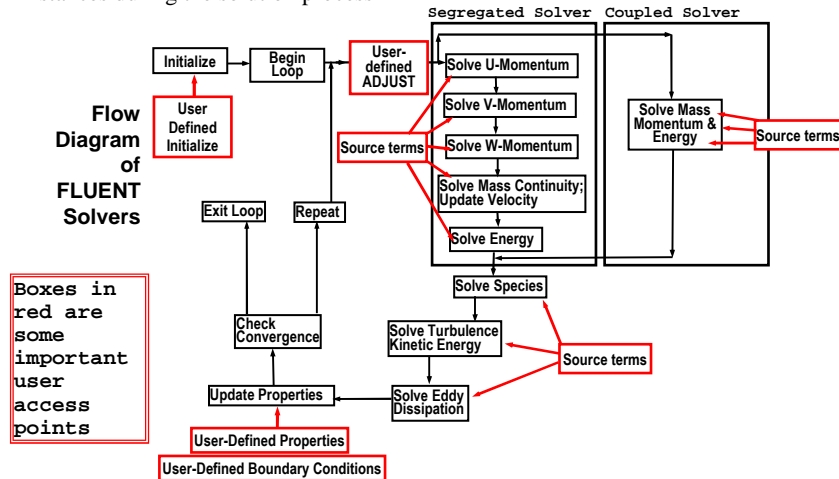
09:15 – 09:30	General Introduction to User Defined Functions
09:30 – 10:00	Fluent Data Structure and Macros
10:00 – 10:15	Break
10:15 – 10:45	Interpreted / Compiled UDF
10:45 – 11:45	UDF Hooks - 'DEFINE' Macros
11:45 – 12:30	Tutorial Session
12:30 – 13:30	Lunch
13:30 – 14:00	User Defined Scalars and Memories
14:00 – 14:30	UDF for Discrete Phase Model
14:30 – 15:00	UDF for Multiphase Flows
15:00 – 15:15	Break
15:15 – 16:00	Tutorial-session-2
16:00 – 16:30	UDF for Parallel FLUENT
16:30 – 17:00	Miscellaneous Functions / Macros

Why Build UDFs?

- Standard interface can not be programmed to anticipate all needs
- Customization of boundary conditions, source terms, reaction rates (volume and surface), properties
- Solution initialization
- Adjust functions (once per iteration)
- Solve for user defined scalars
- Modify model specific parameters
- Many more...
- ◆ Limitations
 - Not all solution variables or solver models can be accessed by UDFs
 - Example: Cannot change specific heat (would require additional solver capabilities)

User Access Points to the Solver

- ◆ Fluent is so designed that the user can access the solver at some strategic instances during the solution process



User Defined Functions in FLUENT

- ◆ User Defined Functions are not just any C-functions:
 - User access needs specific “Type” of function calls
 - These Function types or macros are defined in the header file (e.g., udf.h)
- ◆ UDF's in FLUENT are available for:
 - Profiles (Boundary Conditions)
velocity, temperature, turbulence, species, scalars
 - Source terms (Fluid and solid zones)
mass, momentum, energy, species, turbulence, scalars
 - Properties
viscosity, conductivity, density, scattering_phase_function (except specific heat)
 - Initialization
zone and variable specific initialization
 - Global Functions
adjust, read, write, execute_on_demand
 - Scalar Functions
unsteady term, flux vector, diffusivity
 - Model Specific Functions
reaction rates, discrete phase model, turbulent viscosity



Fluent Data Structure and Macros

Advanced UDF
Modeling Course

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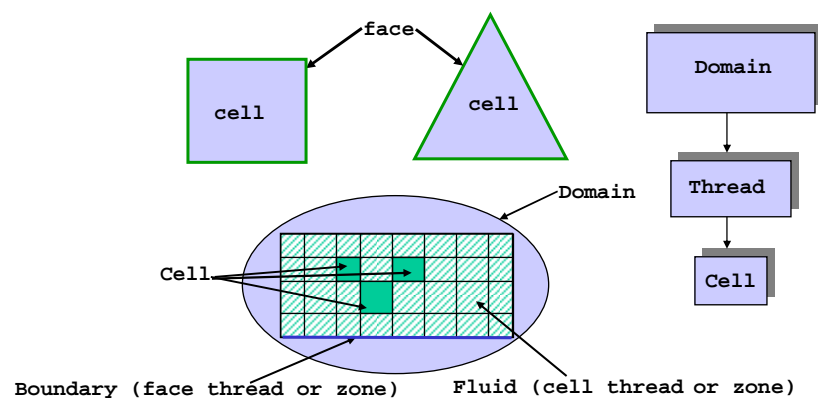
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Data structures in FLUENT



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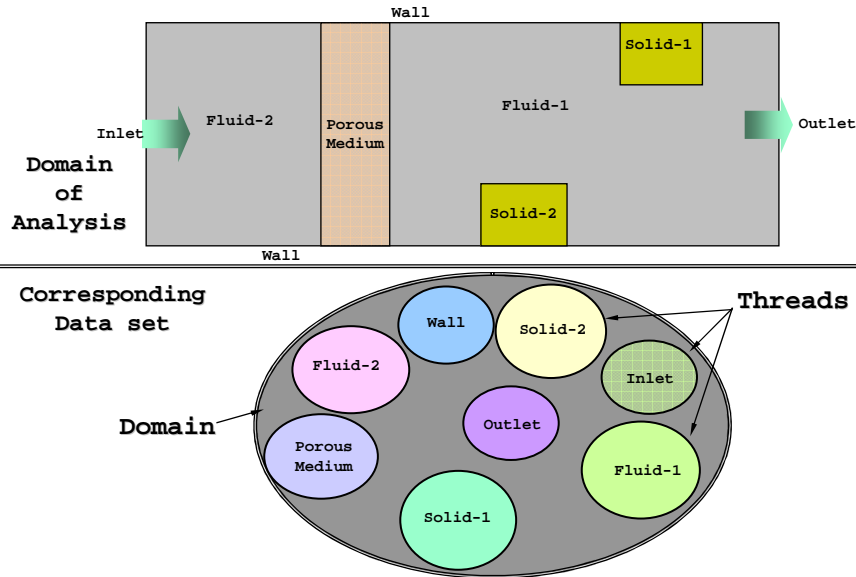
The Domain

- ◆ “Domain” is the set of connectivity and hierarchy info for the entire data structure in a given problem. It includes:
 - » all fluid zones (‘fluid threads’)
 - » all solid zones (‘solid threads’)
 - » all boundary zones (‘boundary threads’)
- ◆ Cell/face - Computational unit, face is one side.
Conservation equations are solved over a cell
- ◆ Thread - is the collection of cells or faces; defines a fluid/solid/boundary zone
- ◆ FLUENT6 introduces the concept of multi-“domain” for multiphase simulations (singlephase simulations use single domain only)
 - Each phase has its own “Domain-structure”
 - Geometric and common property information are shared among ‘sub-domains’
 - Multiphase UDF will be discussed later

The Threads

- ◆ A ‘**Thread**’ is a sub-set of the ‘**Domain**’ structure
- ◆ Individual ‘**fluid**’, ‘**solid**’ and each ‘**boundary**’ zones are identified as ‘**zones**’ and their datatype is maintained as ‘**Thread**’
- ◆ ‘**Zone**’ and ‘**Thread**’ terms are often used interchangeably
- ◆ But **Zone/Thread ID** and **Thread-datatype** are different:
 - Zones are identified at mesh level with an ‘integer’ **ID** in the **Define → Boundary Condition** panel
 - **Threads**, a Fluent-specific datatype, that store structured information about the mesh, connectivity, models, property, etc. all in one place
 - Users identify zones through the **ID**’s
 - **Zone/Thread-ID** and **Threads** are correlated through UDF macro’s

Domain and Threads



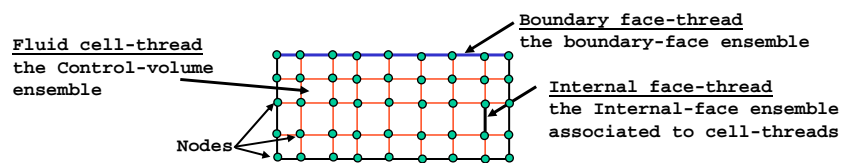
Cell and Face Datatypes

- ◆ Control volumes (equivalent of 'FEM:Elements') of fluid and solid zones are called '**cells**' in FLUENT
 - The data structure for the cell zones is typed as '**cell_t**' (the cell thread)
 - The data structure for the cell faces is typed as '**face_t**' (the face thread)
- ◆ A fluid or solid zone is called a cell zone, which can be accessed by using cell threads
- ◆ Boundary or internal faces can be accessed by using face threads

Some additional info on Faces

- ◆ Each Control volume will have a finite number of faces (4 for tets, 6 for hex and 5 for pyramids, and wedges)
 - ❑ Faces on the boundary are also typed '**face_t**'; their ensemble are listed as boundary **face-threads** with the fluid & solid cell-threads under **Define-Boundary_Condition** panel
 - ❑ Those faces which are inside the flow-domain and do not share any external boundary are not accessible from GUI (because you do not need them)
 - ❑ They can still be accessed from User-Defined-Functions

Cell- & face-Threads

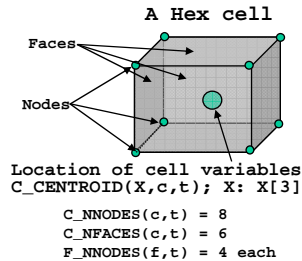


Type	Example	Details
Domain	*d	pointer to the collection of all threads
Thread	*t	pointer to a thread
cell_t	c	cell identifier
face_t	f	face identifier
Node	*node	pointer to a node

Geometry Macros

The argument (c,t) stands for a cell, c of a thread, t

- ◆ C_NNODES(c, t); Number of nodes in a cell
- ◆ C_NFACES(c, t); No. of faces in a cell
- ◆ F_NNODES(f, t); No. of nodes in a face
- ◆ C_CENTROID(x, c, t); x, y, z-coords of cell centroid
- ◆ F_CENTROID(x, f, t); x, y, z-coords of face centroid
- ◆ F_AREA(A, f, t); Area vector of a face;
- ◆ NV_MAG(A); Area-magnitude
- ◆ C_VOLUME(c, t); Volume of a cell
- ◆ C_VOLUME_2D(c, t); Volume of a 2D cell
(Depth is 1m in 2D; $2*\pi$ m in axisymmetric)
- ◆ NODE_X(nn); Node x-coord;
- ◆ NODE_Y(nn); Node y-coord;
- ◆ NODE_Z(nn); Node z-coord;



Looping Macros for Geometry

- ◆ thread_loop_c(t, d); Loop over cell threads
- ◆ thread_loop_f(t, d); Loop over face threads
- ◆ begin_c_loop(c, t); } Loop over cells in a cell thread
- ◆ end_c_loop(c, t); }
- ◆ begin_f_loop } Loop over faces in a face thread
- ◆ end_f_loop }
- ◆ f_edge_loop(f, t,en); Loop over edges in a face thread
- ◆ f_node_loop(f, t,nn); Loop over nodes in a face thread
- ◆ c_node_loop(c, t,nn); Loop over nodes in a cell thread
- ◆ c_face_loop(c, t,fn); Loop over faces in a cell thread

Pointer to a Thread

- Given the integer ID of a **thread**, it is possible to retrieve the pointer to that thread -

```
int ID = 1;
Thread *tf = Lookup_Thread(domain, ID);
```

- Conversely, given the pointer to a **thread**, it is possible to retrieve the integer ID of that **thread** -

```
int ID = 1;
if (THREAD_ID(tf)==1)...
```

```
int ID = 1;
Thread *tf =
    Lookup_Thread(domain, ID);
begin_f_loop(f, tf)
{
    F_CENTROID(FC, f, tf);
    printf("x:%f y:%f", FC[0],
        FC[1]);
}
end_f_loop(f, tf)
```

```
int ID = 1;
thread_loop_f (tf, domain)
{
    if (THREAD_ID(tf)==1)
        begin_f_loop(f, tf)
        {
            F_CENTROID(FC, f, tf);
            printf("x:%f y:%f", FC[0], FC[1]);
        }
    end_f_loop(f, tf)
}
```

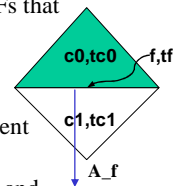
Cells across a face and Their Threads

- These macros identify the neighboring cells of a face
- This information may be required of some of the more sophisticated UDFs that loop through
 - faces of a boundary thread or
 - a particular cell

- Associated with a given face *f*, and its thread *tf*, are potentially two adjacent cells denoted *c0* and *c1* (face normals are always pointing outwardly)
 - If the face is on the boundary of the domain, *c1* is defined as NULL and only *c0* exists

- The following macros return the ID of the cells *c0* and *c1*, as well as the associated threads:

```
c0 = F_C0(f, tf); /* returns thread ID for cell c0 */
tc0 = THREAD_T0(tf); /* returns the cell thread pointer for c0 */
c1 = F_C1(f, tf); /* returns thread ID for c1 */
tc1 = THREAD_T1(tf); /* returns the cell thread pointer for c1 */
```



Cell Variables

(1)

- ◆ $C_R(c, t)$ Density
- ◆ $C_P(c, t)$ Pressure
- ◆ $C_U(c, t)$ } Velocity components
- ◆ $C_V(c, t)$ }
- ◆ $C_W(c, t)$ }
- ◆ $C_T(c, t)$ Temperature
- ◆ $C_H(c, t)$ Enthalpy
- ◆ $C_K(c, t)$ Turbulent kinetic energy
- ◆ $C_D(c, t)$ Turbulent energy dissipation
- ◆ $C_YI(c, t, i)$ Species mass fraction
- ◆ $C_UDSI(c, t, i)$ User defined scalar

Cell Variables

(2)

- ◆ $C_DUDX(c, t)$ } Velocity derivatives
- ◆ $C_DUDY(c, t)$ }
- ◆ $C_DUDZ(c, t)$ }
- ◆ $C_DVDX(c, t)$ }
- ◆ $C_DVDY(c, t)$ }
- ◆ $C_DVDZ(c, t)$ }
- ◆ $C_DWDX(c, t)$ }
- ◆ $C_DWDY(c, t)$ }
- ◆ $C_DWDZ(c, t)$ }
- ◆ $C_MU_L(c, t)$ } Viscosities
- ◆ $C_MU_T(c, t)$ }
- ◆ $C_MU_EFF(c, t)$ }
- ◆ $C_DP(c, t)[i]$ Pressure derivatives
- ◆ $C_D_DENSITY(c, t)[i]$ Density derivatives

Cell Variables

(3)

- ◆ $C_K_L(c, t)$
 - ◆ $C_K_T(c, t)$
 - ◆ $C_K_EFF(c, t)$
 - ◆ $C_CP(c, t)$
 - ◆ $C_RGAS(c, t)$
 - ◆ $C_DIFF_L(c, t, i)$
 - ◆ $C_DIFF_EFF(c, t, i)$
- } Thermal conductivities
 Specific heat
 Gas constant
 } Species diffusivity

Face Variables

- ◆ $F_P(f, t)$
 - ◆ $F_U(f, t)$
 - ◆ $F_V(f, t)$
 - ◆ $F_W(f, t)$
 - ◆ $F_T(f, t)$
 - ◆ $F_H(f, t)$
 - ◆ $F_K(f, t)$
 - ◆ $F_D(f, t)$
 - ◆ $F_YI(f, t, i)$
 - ◆ $F_UDSI(f, t, i)$
 - ◆ $F_PROFILE(f, t, i)$
- Pressure
 } Velocity components
 Temperature
 Enthalpy
 Turbulent kinetic energy
 Turbulent energy dissipation
 Species mass fraction
 User defined scalar
 Boundary profile storage

UDF Macro-s (Types of UDF)

◆ UDF's in FLUENT are available for:

- Boundary conditions : Profiles
- Fluid and solid zones : Source terms
- Fluid/solid, particle, flow : Properties
- UDS unsteady, flux, diffusivity : Scalar Functions
- Zone and variable specific initialization : Initialization
- Adjust, read/write, execute_on_demand : Global Function
- Convective & radiative : Wall-heat-flux
(Alternative: profile)
- Reaction rates, dpm, slip velocity,... : Model Specific Functions

UDF Macro-s (Types of UDF)

◆ Available UDF Macro-s :

- Profiles : DEFINE_PROFILE
- Source terms : DEFINE_SOURCE
- Properties : DEFINE_PROPERTY
- Scalar Functions : DEFINE_UNSTEADY
DEFINE_FLUX
DEFINE_DIFFUSIVITY
- Initialization : DEFINE_INIT
- Global Functions : DEFINE_ADJUST
DEFINE_ON_DEMAND
DEFINE_RW_FILE
- Wall-heat-flux : DEFINE_HEAT_FLUX
- Model Specific Functions : DEFINE_DPM_...
DEFINE_SR_RATE
DEFINE_VR_RATE
DEFINE_SCAT_PHASE_FUNC
DEFINE_DRIFT_DIAMETER
DEFINE_SLIP_VELOCITY

The udf.h File

- ◆ The udf-macros are defined in the 'udf.h' file
- ◆ **udf.h** is a fluent header file in the ~/Fluent.Inc/Fluentx.y/src/ directory
- ◆ **udf.h** must be included at the top in each and every udf file
 - A file may contain more than one UDF
 - User can use multiple files for UDF
- ◆ Any UDF you might write must use one of the 'DEFINE_...' macros from this **udf.h** file

Part of the 'udf.h' file from ~/Fluent.Inc/fluentx.y/src directory

```
#define DEFINE_PROFILE(name, t, i) void name(Thread *t, int i)
#define DEFINE_PROPERTY(name,c,t) real name(cell_t c, Thread *t)
#define DEFINE_SOURCE(name, c, t, dS, i) \
    real name(cell_t c, Thread *t, real dS[], int i)
#define DEFINE_INIT(name, domain) void name(Domain *domain)
#define DEFINE_ADJUST(name, domain) void name(Domain *domain)
#define DEFINE_DIFFUSIVITY(name, c, t, i) \
    real name(cell_t c, Thread *t, int i)
```



Interpret / Compile UDFs and Their Usage

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How to use the UDF

- ◆ First, we need to write and save the C-source file containing the appropriate **DEFINE_MACRO** routine(s).
- ◆ To use this file, the steps are:
 - 1: Interpret / Compile the UDF
 - 2: Start the solver (FLUENT) and read in your case/data files
 - 3: Assign the UDFs in the BC and/or other panels for the appropriate zones
 - 4: Set the UDF update frequency in the Iterate panel
 - 5: Run the calculation as usual
- ◆ **Note:** Values obtained from and returned to the solver by UDFs must be in SI units

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Interpreted Vs. Compiled Code

- ◆ UDFs can be 'interpreted' on-the-fly using the standard 'GUI'
 - does not need a separate compiler and are architecture-independent
 - It translates the C-source to assembly language
 - Executes the code on line-by-line instantaneously
 - performs slower than compiled UDFs
 - The interpreter resides in the computer's memory
 - involves extra memory usage
- ◆ UDFs can be precompiled before invoking in FLUENT
 - Needs a compiler
 - It translates the C-source to machine language (object modules)
 - Needs to follow a standard multi-step procedure (will be discussed later)
 - Creates 'shared libraries' linked with the rest of the solver

ALL INTERPRETED UDF-S CAN ALSO BE COMPILED
THOUGH THE CONVERSE IS NOT TRUE

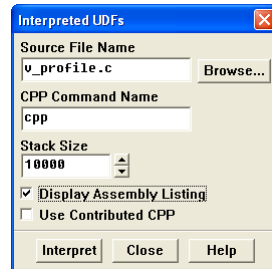
Interpreted UDFs

- ◆ Interpreter limitations:
 - mixed mode arithmetic,
 - structure references etc.
 - cannot be linked to compiled system or user libraries
 - less powerful than compiled UDFs due to limitations in the C language supported by the interpreter
- ◆ In particular, interpreted UDFs cannot contain:
 - non ANSI-C prototypes for syntax
 - declarations of local structures, unions, pointers to functions, and arrays of functions
 - direct structure references
- ◆ Interpreted UDFs can indirectly access data stored in a FLUENT structure only via a set of macro-s

Interpreting the UDF

(2)

- Define → User Defined Functions → Interpreted...



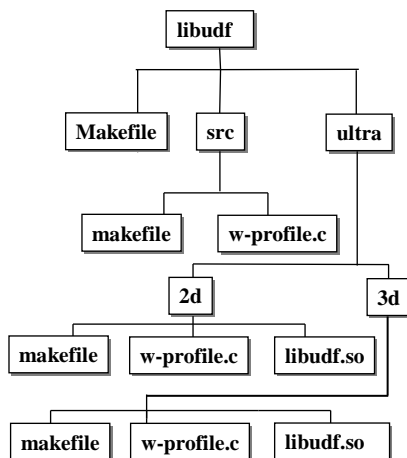
- Click Interpret
- The assembly language code will scroll past window

Listing appearing on Fluent windows:

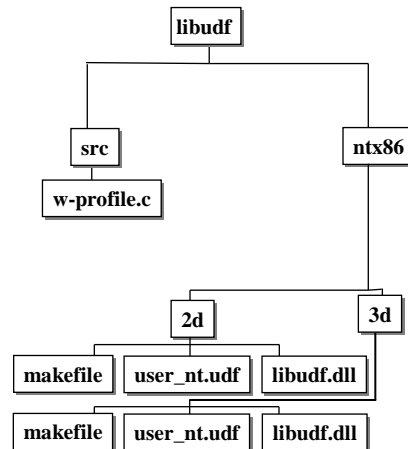
```
w_profile:
    .local.pointer thread (r0)
    .local.int position (r1)
0   .local.end
0   save
    .local.int f (r6)
8   push.int 0
10  save
    .local.int.
    .:
    .: } Skipping display here
.L1:
132 restore
133 restore
134 ret.v
```

Compiled UDF Directory Structure

Unix Tree

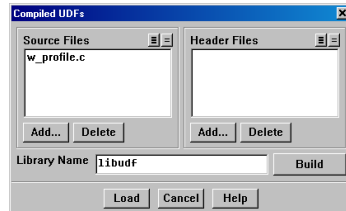


Windows Tree



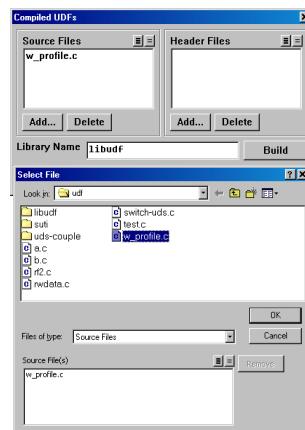
UDF Compilation in F6.2

- ◆ To compile UDFs from within Fluent, use:
 - Define→User_Defined→Functions→Compile...
- ◆ Placing source routines in your working directory would be sufficient and necessary
- ◆ This GUI creates the directory structure below your working directory where you have your case and data files
- ◆ This GUI identifies the architecture as well as the version of fluent running and compiles only for the appropriate UDF version (2d/2ddp/3d/3ddp/or any parallel version)



UDF Compilation in F6.2

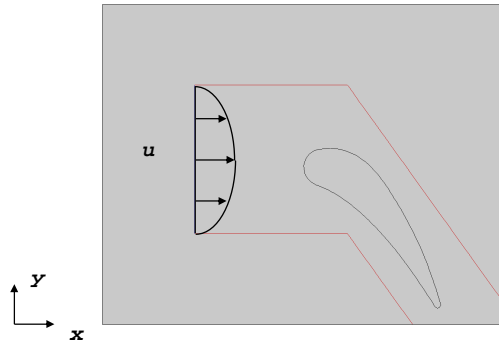
- ◆ Define→User_Defined Functions→Compile...
- ◆ Click on the “Add” button to browse and add source and header files
- ◆ Click on “Build” button to compile and then “Load” to load the library to a case file
- ◆ The compilation log appears on the Fluent console window and in a file named log
- ◆ To unload a compiled UDF, use Define→User_Defined Functions→Manage, select the library, then click Unload button



Using UDFs - Example

- ♦ A non-uniform inlet velocity is to be imposed on the 2D turbine vane shown below. The x-velocity variation is to be specified as

$$u(y) = 20 [1 - (y/0.067)^2]$$



A Source Code Example

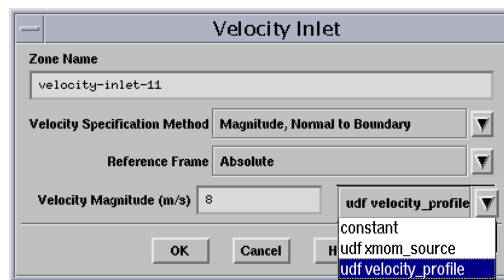
```
#include "udf.h"

DEFINE_PROFILE(velocity_profile, thread, position)
{
    real x[3]; /* this will hold the position vector*/
    real y;
    face_t f;

    begin_f_loop(f, thread)
    {
        F_CENTROID(x,f,thread);
        y = x[1];
        F_PROFILE(f, thread, position) = 20.*(1.- y*y /
                                                (.067*.067));
    }
    end_f_loop(f, thread)
}
```

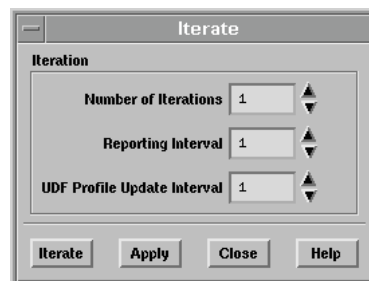
Activating the UDF

- ◆ Access the **boundary condition** panel
- ◆ Switch from **constant** to the **UDF** function in the **Velocity Magnitude** dropdown list



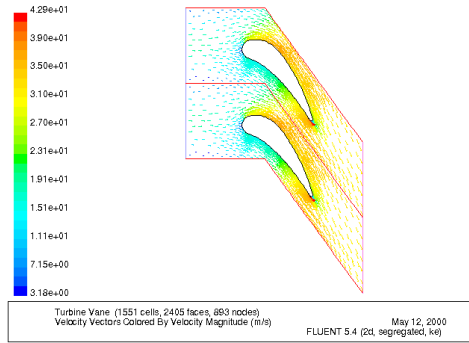
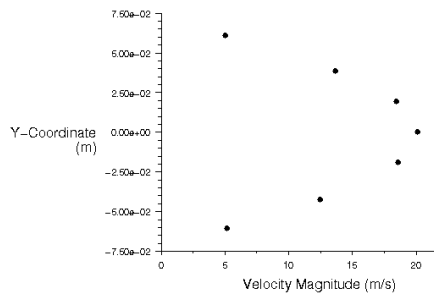
Run the Calculation

- ◆ Run the calculation as usual
- ◆ You can change the **UDF Profile Update Interval** in the **Iterate panel** (here it is set to 1)



Solution of Example problem

- ◆ The figure at right shows velocity field throughout turbine blade passage
- ◆ The bottom figure shows the velocity plot at the inlet
- ◆ Notice the imposed parabolic profile





UDF Hooks --- 'DEFINE' Macros

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Boundary Profiles: DEFINE_PROFILE

- ◆ You can use this UDF to specify
 - Wall
 - temperature
 - heat flux, shear stress
 - Inlets
 - velocity
 - temperature
 - turbulence
 - species
 - scalars
- ◆ The macro **begin_f_loop** loops over all faces on the selected boundary thread
- ◆ The **F_PROFILE** macro applies the value to face, **f** on the **thread**

It's a must!

```
#include "udf.h"

DEFINE_PROFILE(w_profile, thread, position)
{
    face_t f;
    real b_val;

    begin_f_loop(f, thread)
    {
        b_val = .../* your boundary value*/
        F_PROFILE(f, thread, position) = b_val;
    }
    end_f_loop(f, thread)
}
```

User specified name

Arguments from the solver to this UDF

thread : The thread of the boundary to which the profile is attached

position : A solver internal variable (identifies the stack location of the profile in the data stack)

User can rename the variables at will:

```
DEFINE_PROFILE(my_prof, t, pos)
```

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Example 1: Transient Inlet Velocity

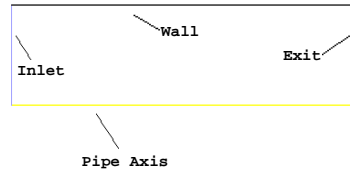
- ◆ Pulsatile flow in a tube

$$V_x = V_0 + A \sin(\omega t)$$

where $V_0 = 20$ m/s, $A = 5$ m/s, $\omega = 10$ rad/s

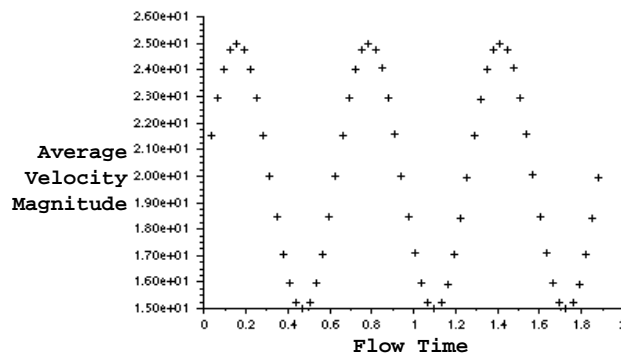
- ◆ Boundary condition is applied at inlet

```
#include "udf.h"
DEFINE_PROFILE(unsteady_v, t, pos)
{
    real time, velocity;
    face_t f;
    begin_f_loop(f, t)
    {
        time = RP_Get_Real("flow-time");
        velocity = 20.0 +
            5.0*sin(10.*time);
        F_PROFILE(f, t, pos) = velocity;
    }
    end_f_loop(f, t)
}
```



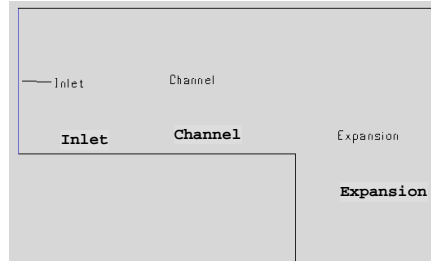
Example 1: Results of Transient Inlet Velocity

- ◆ Time history of the average velocity at the pipe exit shows sinusoidal oscillation with a mean of 20 and amplitude of 5.



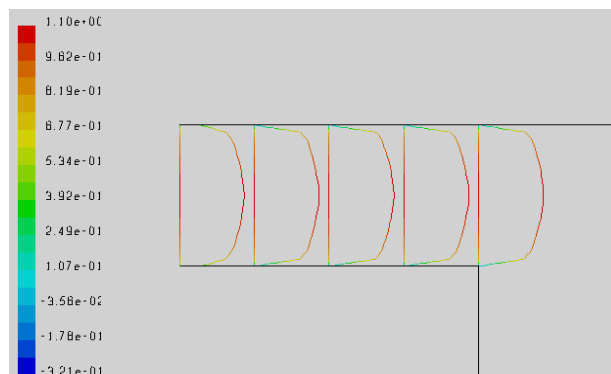
Example 2: Fully Developed Turbulent Inlet

- ◆ Profiles for inlet velocity, k and ϵ are used to approximate fully developed flow conditions
- ◆ Velocity profile follows 1/7 power law
- ◆ Turbulent kinetic energy varies linearly from a near-wall peak to a prescribed core-flow value
- ◆ Dissipation is prescribed by a mixing-length model
- ◆ Used to minimize the domain size and sensitivity to inlet boundary conditions



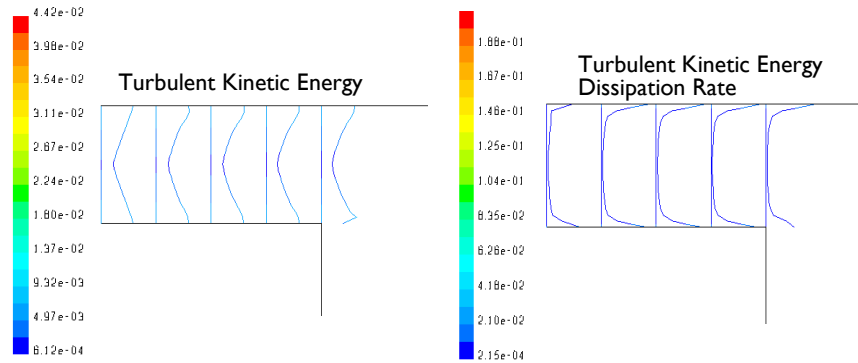
Example 2: Results of Fully Developed Turbulent Inlet

- ◆ Axial velocity profile changes little downstream of inlet boundary



Example 2: Results of Fully Developed Inlet

- ◆ Turbulence quantities change little downstream of the inlet

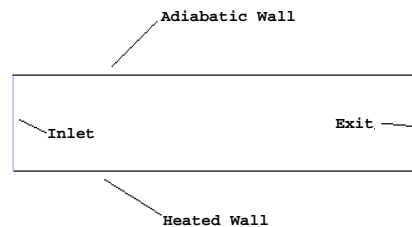


Example 3: Sinusoidal Wall Temperature

- ◆ Lower wall temperature varies sinusoidally with x-position according to

$$T_x = 300 + 100 \sin(\pi x/L)$$

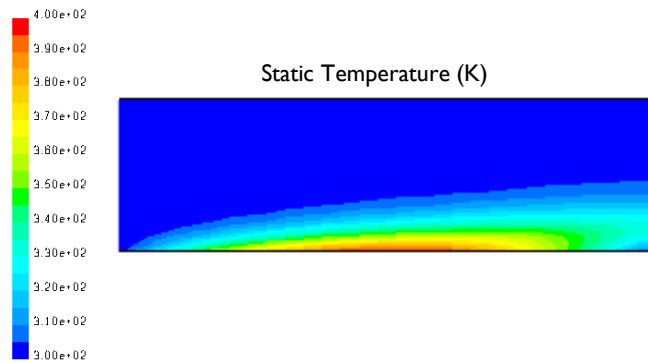
- ◆ Inlet fluid enters at 300 K
- ◆ Upper wall is insulated



Temperature: `F_PROFILE(f, t, pos) = 300.+100.*sin(PI*x/0.005);`

Example 3: Results of Sinusoidal Wall Temperature

- ♦ Wall (and fluid) temperature reaches peak at midlength of channel



Source Terms (1)

- ♦ The solvers compute source terms using the “linearized form”

$$S = A + B \phi$$

where ϕ is the dependent variable, A is the explicit part of the source term and $B\phi$ is the implicit part

- ♦ A recommended linearization is $S = S^* + \left(\frac{\partial S}{\partial \phi} \right)^* (\phi - \phi^*)$
where ϕ is the dependent variable

- ♦ FLUENT Solver will automatically determine whether the user-supplied source is enhancing the numerical stability (namely, the diagonal dominance of the system matrix)

Source Terms (2)

- ◆ Source term UDFs can be created for the governing equations:
 - continuity
 - momentum
 - k, ϵ
 - energy
 - species
 - User-defined scalars
- ◆ Energy source term UDFs may also be defined for solid zones
- ◆ NOTE: The units of all source terms are expressed in terms of the volumetric generation rate. For example, a source term for the continuity equation would have units of (kg/s/m^3)

Source Terms (3)

- ◆ Solver call this UDF for each cell in the zone
- ◆ The solver passes the UDF the cell pointer associated with the cell
- ◆ The variable `ds[eqn]` sets up the implicit part of the source term for the equation the source term is used for
- ◆ Note that the UDF returns a real value for the explicit part of the source, the implicit part `ds[eqn]` is returned in a referenced array

```
include "udf.h"

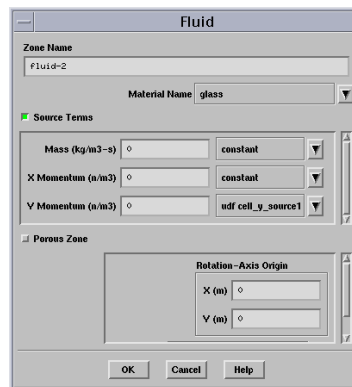
DEFINE_SOURCE(cell_y_source1,
              cell, thread, ds, eqn)
{
  real source;

  /* S = source + ds[eqn]*phi */
  ds[eqn] = /* expression */
  source = /* expression */

  return source;
}
```

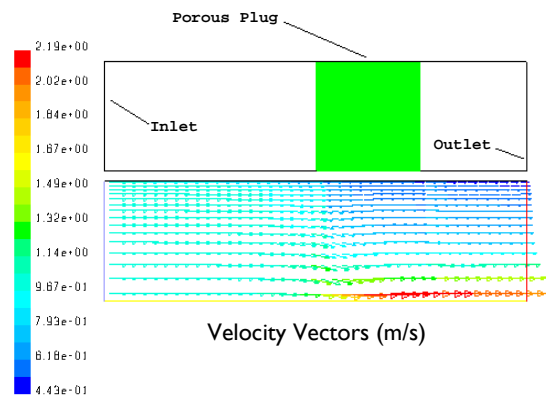
Source Terms (4)

- ◆ To activate source terms **Define** ☒ **Boundary Conditions** ☒ **fluid-1** and click on **Source Terms**



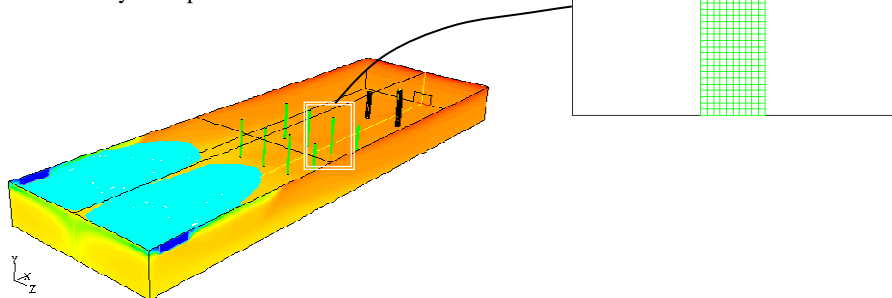
Example 4: Position Dependent Porous Media

- ◆ Channel flow with porous plug
- ◆ x-momentum loss is linear in y-position, starting from zero at lower wall
- ◆ Fluid flows preferentially near the bottom of the channel



Example 5: Bubble Generated Momentum

- ◆ A column of bubbles imparts vertical momentum inside a sparging tank.
- ◆ The rate of momentum addition is correlated to bubble size and number density.
- ◆ This simple model can be used in place of a more costly multiphase model.



Example 5: Bubble Generated Momentum

- ◆ The rising plume of bubbles creates circulation throughout the tank

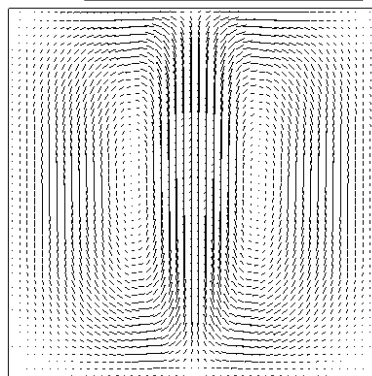
```
#include "udf.h"
real bubbler_vol=0.0; /*static variable*/
DEFINE_SOURCE(mom_y_src, c, t, rj, eqn)
{
#define PI 3.14159
#define GRAV 9.81
#define bub_rad 1.e-3
real bub_vel, f_d, bub_freq=5., bubbler_ht=1.;
float bub_num, source;
cell_t cc;
rj[eqn] = 0.0;
if(bubbler_vol == 0.) /*Bubbler volume*/
{begin_c_loop(cc, t)
bubbler_vol=bubbler_vol+C_VOLUME(cc,t);
end_c_loop(cc, t)}
/* Calculate force for single bubble */
bub_vel=GRAV*pow(bub_rad,2.)*C_R(c,t)/
(3.*C_MU_L(c,t));
f_d =4.*PI*C_MU_L(c,t)*bub_rad*bub_vel;
bub_num = (bub_freq*bubbler_ht/bub_vel);
source = bub_num*f_d*100./bubbler_vol;
return source;
}
```

$$v = g \cdot r^2 \cdot \rho / (3 \cdot \mu)$$

$$\text{Drag} = 4 \cdot \pi \cdot \mu \cdot r \cdot v$$

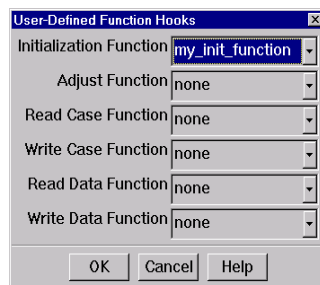
$$N = f \cdot h / v$$

$$\text{Source} = N \cdot \text{Drag} \cdot 100 / \text{Volume}$$

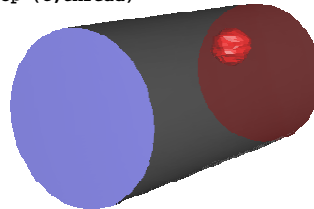


Initialization and Example 6

- ◆ Initializes solutions for entire domain, similar to “patching” of values
- ◆ Executed once at the beginning of solution process
- ◆ Initialization Function appears under **Define**→**User Defined**→**Function hooks...**

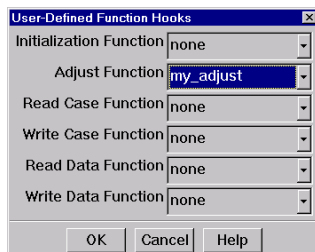


```
#include "udf.h"
DEFINE_INIT(my_init_function, domain)
{
    cell_t c;
    Thread *thread;
    real xc[ND_ND];
    thread_loop_c (thread, domain)
    {
        begin_c_loop (c, thread)
        {
            C_CENTROID(xc, c, thread);
            if (sqrt(ND_SUM(pow(xc[0]-0.5, 2.),
                pow(xc[1] - 0.5, 2.),
                pow(xc[2] - 0.5, 2.))) < 0.25)
                C_T(c, thread) = 400.;
            else
                C_T(c, thread) = 300.;
        }
        end_c_loop (c, thread)
    }
}
```



Adjust Function and Example 7

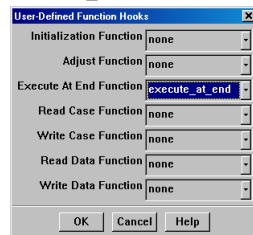
- ◆ Function called for every iteration
- ◆ Integrate the turbulent dissipation over the whole domain and print it to the text user interface
- ◆ Adjust Function appears under **Define**→**User Defined**→**Function hooks...**



```
DEFINE_ADJUST(my_adjust, domain)
{
    /* Integrate dissipation. */
    real sum_diss=0.;
    Thread *t;
    cell_t c;
    thread_loop_c (t, domain)
    {
        begin_c_loop (c, t)
        {
            sum_diss += C_D(c, t) * C_VOLUME(c, t);
        }
        end_c_loop (c, t)
    }
    Message("Volume integral of turbulent
        dissipation : %g\n", sum_diss);
}
```

Execute_at_End Function and Example 8

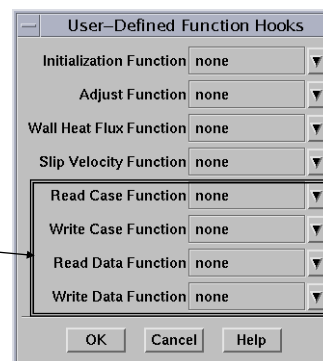
- ◆ This is a general purpose macro executed at the end of
 - an iteration in a steady state run, or
 - at the end of a time step in a transient run.
- ◆ UDF for integrating turbulent dissipation and printing it to console window at the end of the current iteration or time step
- ◆ This Function appears under Define → User Defined → Function hooks...



```
#include "udf.h"
DEFINE_EXECUTE_AT_END(execute_at_end)
{
    Domain *d; Thread *t;
    real sum_diss=0.;
    cell_t c;
    d = Get_Domain(1);
    thread_loop_c (t,d)
    {
        if (FLUID_THREAD_P(t))
        {
            begin_c_loop (c,t)
            {
                sum_diss+=C_D(c,t)*C_VOLUME(c,t);
            }
            end_c_loop (c,t)
        }
    }
    printf("Volume integral of turbulent
    dissipation: %g\n", sum_diss);
    fflush(stdout);
}
```

User Defined I/O

- ◆ Ability to read/write custom data in case/data files
 - Can save and restore custom variables of any data types (e.g., integer, real, Boolean, structure)
 - Useful to save “dynamic” information (e.g., number of occurrences in conditional sampling)
 - Defined using **DEFINE_RW_FILE** macro
 - Selected in the User-Defined Function Hooks panel



User Defined I/O (2)

```
#include "udf.h"
int count = 0; /* define and initialize static variable
count */
DEFINE_ADJUST(it_count, domain)
{
    count++;
    printf("count = %d\n",count);
}
DEFINE_RW_FILE(writer, fp)
{
    printf("Writing UDF data to data file...\n");
    fprintf(fp, "%d",count); /* write out count to data
file */
}
DEFINE_RW_FILE(reader, fp)
{
    printf("Reading UDF data from data file...\n");
    fscanf(fp, "%d",&count); /* read count from data file
*/
}
```

Properties and Example 9

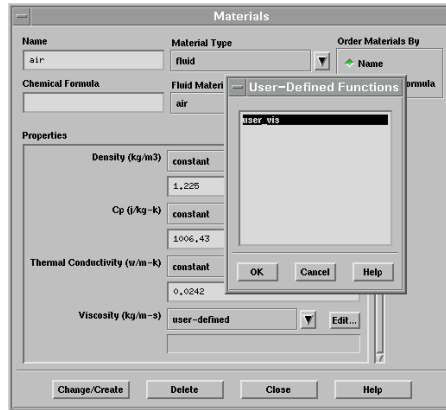
- ◆ UDF's can be used to define
 - Viscosity
 - Thermal Conductivity
 - Mass Diffusivity
 - Density
- ◆ UDF's cannot be used to define specific heat
- ◆ The function is called for every cell in the zone

$$\mu = \begin{cases} 5.5 \cdot 10^{-3} & T > 288K \\ 143.2 - 0.49725T & 286K \leq T \leq 288K \\ 1 & T < 286K \end{cases}$$

```
#include "udf.h"
DEFINE_PROPERTY(user_vis, cell, thread)
{
    real temp, mu_lam;
    temp = C_T(cell, thread);
    {
        if (temp > 288.)
            mu_lam = 5.5e-3;
        else if (temp >= 286. && temp <= 288.)
            mu_lam = 143.2135 - 0.49725 * temp;
        else
            mu_lam = 1.0;
    }
    return mu_lam;
}
```

Properties (2)

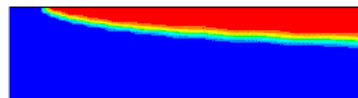
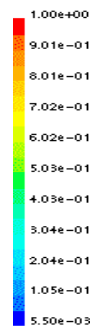
- ◆ To activate the UDF, select user-defined from the property drop down list
- ◆ When you select the user-defined option, a panel will appear with the names of your UDF's
- ◆ Select the name of the appropriate UDF



Example 10: Temperature Dependent Viscosity

- ◆ Warm fluid enters the channel flowing from left to right.
- ◆ Viscosity increases as the fluid is cooled by contact with the cold upper wall.

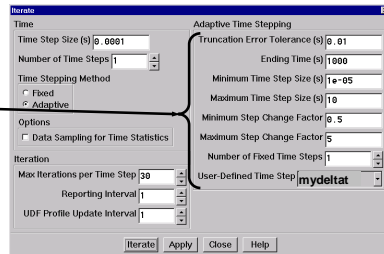
```
#include "udf.h"
DEFINE_PROPERTY(user_vis, cell, thread)
{
    real temp, mu_lam;
    temp = C_T(cell, thread);
    /* Limit viscosity for high temperature */
    if (temp > 288.) mu_lam = 5.5e-3;
    /* Otherwise, use a profile for viscosity */
    else if (temp >= 286. && temp <= 288.)
        mu_lam = 143.2135-0.49725*temp;
    else
        mu_lam = 1.0;
    return mu_lam;
}
```



Contours of molecular viscosity (kg/ms)

Time Step: DEFINE_DELTAT

- ◆ In Fluent, you may use adaptive timestepping based on minimum and maximum values of timesteps as well as other parameters
- ◆ Adaptive timestepping is activated by selecting the corresponding radio-button in the **Solve-Iterate** panel for unsteady problems
- ◆ **DEFINE_DELTAT** lets the user control the timestep based on any custom logic/algorithm



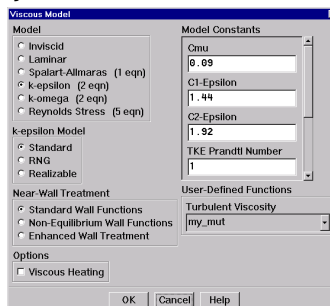
```
#include "udf.h"
DEFINE_DELTAT(mydeltat, domain)
{
    real time_step;
    real flow_time =
        RP_Get_Real("flow-time");
    if (flow_time < 0.5)
        time_step = 0.1;
    else
        time_step = 0.2;
    return time_step;
}
```

Turbulent Viscosity: DEFINE_TURBULENT_VISCOSITY

- ◆ Any custom relation for the turbulent viscosity formulation can be adopted using this UDF hook
- ◆ The variable names for the constants in the standard k-ε model are:

- C_1 : **M_keC1**
- C_2 : **M_keC2**
- C_μ : **M_keCmu**
- σ_k : **M_keigk**
- σ_ϵ : **M_keige**
- σ_ϵ : **M_keprt**

```
DEFINE_TURBULENT_VISCOSITY(my_mut, cell, thread)
{
    real mu_t;
    real rho = C_R(cell, thread);
    real k = C_K(cell, thread);
    real epsilon = C_D(cell, thread);
    mut = M_keCmu * rho * SQRT(k) / epsilon;
    return mut;
}
```

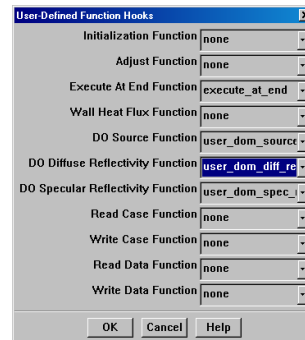


$$\mu_t = C_\mu \rho \frac{k^2}{\epsilon}$$

Radiation Reflectivity: Discrete Ordinate Model Only

- ◆ **Diffused Reflectivity**
- ◆ Modify the interfacial reflectivity at **diffusely** reflecting semi-transparent walls, based on the refractive index
- ◆ This function is called for each semi-transparent wall and each band (non-gray DO Model)
- ◆ The function can be used to modify interface values of diffuse reflectivity and diffuse transmissivity
- ◆ In this example, reflectivity values are not customized: they are just printed

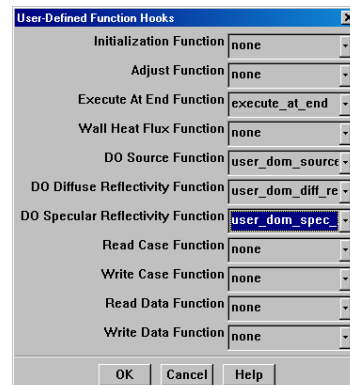
```
#include "udf.h"
DEFINE_DOM_DIFFUSE_REFLECTIVITY
(user_dom_diff_refl, t, nband,
n_a, n_b, diff_ref_a, diff_tran_a,
diff_ref_b, diff_tran_b)
{
    printf("diff_ref_a=%f diff_tran_a=%f\n",
           *diff_ref_a, *diff_tran_a);
    printf("diff_ref_b=%f diff_tran_b=%f \n",
           *diff_ref_b, *diff_tran_b);
}
```



Radiation Reflectivity: Discrete Ordinate Model (2)

- ◆ **Specular Reflectivity**
- ◆ Modify the **specular** reflectivity and transmittivity at semi-transparent walls, along direction s at a face (f)
- ◆ The same UDF is called for all the faces of the semi-transparent wall, for each of the directions

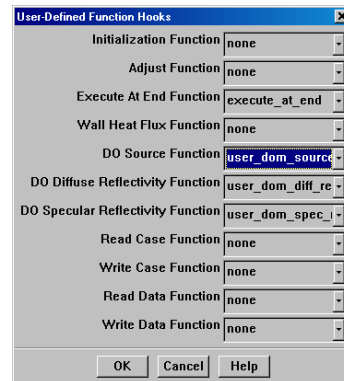
```
#include "udf.h"
DEFINE_DOM_SPECULAR_REFLECTIVITY
(user_dom_spec_refl, f, t, nband, n_a,
n_b,
ray_direction, en,
internal_reflection,
specular_reflectivity,
specular_transmissivity)
{
    real angle, cos_theta;
    real PI = 3.141592;
    cos_theta = NV_DOT(ray_direction, en);
    angle = acos(cos_theta);
    if (angle > 45 && angle < 60)
    {
        *specular_reflectivity = 0.3;
        *specular_transmissivity = 0.7;
    }
}
```



Emission & Scattering: Discrete Ordinate Source Macro

- ◆ Can be used to modify the emission and scattering terms in the radiative transport equation

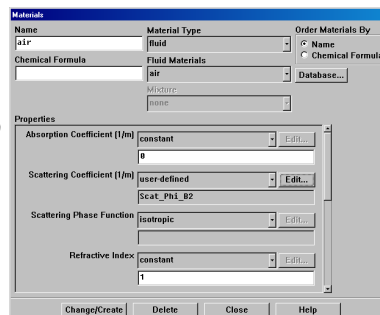
```
#include "udf.h"
DEFINE_DOM_SOURCE(user_dom_source,
c, t, ni, nb, emission,
in_scattering, abs_coeff,
scat_coeff)
{
    *emission *= 1.05;
}
```



Scattering Phase Function: Discrete Ordinate Model

- ◆ Define the radiation scattering phase function for the Discrete Ordinates (DO) model
- ◆ The function computes two values: the fraction of radiation energy scattered from direction *i* to direction *j*, and the forward scattering factor
- ◆ Look at the UDF manual for a complete listing of the UDF for backward and forward scattering phase functions after Jendoubi et al *J. Thermophys. Heat Transfer*, 7(2):213-219, 1993
- ◆ This function is loaded as user-defined scattering coefficient in the materials panel

```
#include "udf.h"
DEFINE_SCAT_PHASE_FUNC(Scat_Phi_B2,c,fsf)
{
    real phi=0;
    *fsf = 0;
    phi = 1.0 - 1.2*c + 0.25*(3*c*c-1);
    return (phi);
}
```

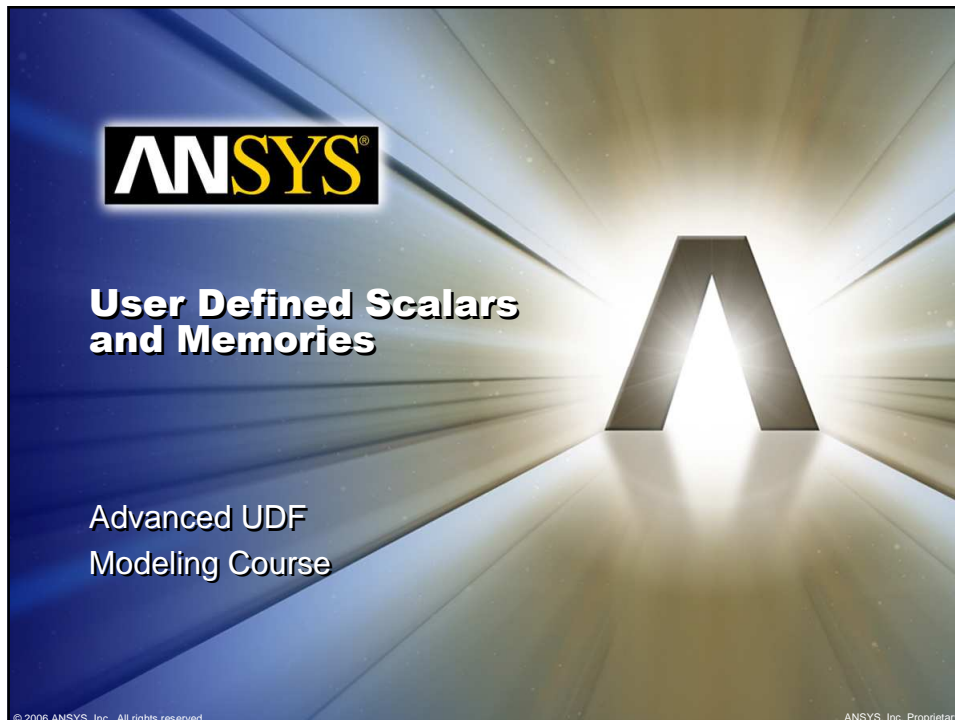


Additional Macros

- ◆ There are a number of additional model specific macros
 - You can learn more about these from the UDF manual section 4.3

```
DEFINE_CHEM_STEP( name, ifail, n, dt, p, temp, yk)
DEFINE_NET_REACTION_RATE( name, p, temp, yi, rr, jac)
DEFINE_NOX_RATE ( name, c, t, NOx)
DEFINE_PRANDTL_D ( name, c, t)
DEFINE_PR_RATE ( name, c, t, r, mw, ci, p, sf,
                 dif_index, cat_index, rr)
DEFINE_SR_RATE ( name, f, t, r, my, yi, rr)
DEFINE_VR_RATE ( name, c, t, r, mw, yi, rr, rr_t)
DEFINE_TURB_PREMIX_SOURCE ( name, c, t, turb_flame_speed,
                             source)
```

- ◆ Multiphase specific macros will be discussed later



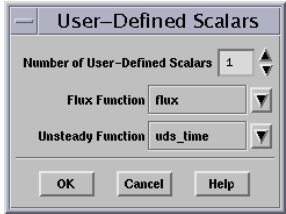
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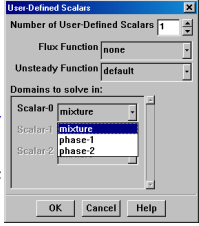
User Defined Scalars (1)

- ◆ FLUENT can solve generic transport equations for User Defined Scalars
- ◆ The menu is accessed through **Define→Models→User-Defined Scalars...**
- ◆ User specifies number of User- Defined Scalars and UDF can be used for parts of scalar transport equation :
 - Advective: `DEFINE_UDS_FLUX`
 - Unsteady: `DEFINE_UDS_UNSTEADY`
 - Diffusivity: `DEFINE_DIFFUSIVITY`



$$\frac{\partial}{\partial t}(\rho\phi) + \frac{\partial}{\partial x_j}(\rho u_j\phi) = \frac{\partial}{\partial x_j}\left(D \frac{\partial \phi}{\partial x_j}\right) + S$$

$$\frac{\partial}{\partial t}(\alpha\phi) + \frac{\partial}{\partial x_j}(\alpha u_j\phi) = \frac{\partial}{\partial x_j}\left(D \frac{\partial \phi}{\partial x_j}\right) + S$$



Scalars are phase-specific in multiphase models
Will be discussed later

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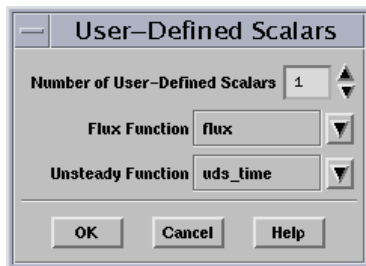
5-2

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User Defined Scalars (2)

- User Defined Scalar convective and time derivatives can be modified

```
DEFINE_UDS_FLUX(flux, f, t, i)
{
    if (i == 0) return 0.;
    if NNULLP(THREAD_STORAGE(t,SV_FLUX))
        return F_FLUX(f,t);
    return 0.;
}
```

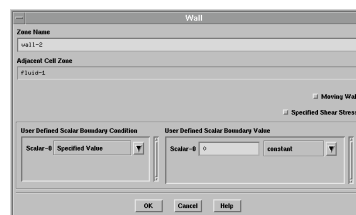


```
DEFINE_UDS_UNSTEADY(uns_time, cell,
    thread, i, apu, su)
{
    real physical_dt, vol, rho, phi_old;
    physical_dt = RP_Get_Real("physical-
    time-step");
    vol = C_VOLUME(cell,thread);

    rho = Rhod;
    *apu = -rho*vol /
    physical_dt;/*implicit part*/
    phi_old =
    C_STORAGE_R(cell,thread,SV_UDSI_M1(
    i));
    *su =
    rho*vol*phi_old/physical_dt;/*expli
    cit part*/
}
```

User Defined Scalars (3)

- The Boundary Conditions for the User Defined Scalar can be specified as **Specified Flux** or **Specified Value**
- The diffusivity for the User Defined Scalar can be specified through **Material**→**user-defined**→**diffusivity** panel as a constant or as User-Defined Function



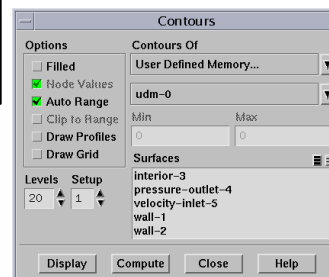
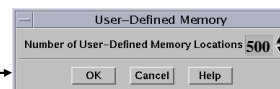
User Defined Scalars (4)

- ◆ The User Defined Scalars and their gradients can be used in UDF's

```
DEFINE_ADJUST(adjust_fcn, domain)
{
    Thread *t;
    int nt;
    cell_t c;
    face_t f;
    int ns;
    real p_dis = 0.;
    /* Do nothing if gradient isn't allocated yet. */
    if (! Data_Valid_P()) return;
    /* Compute power dissipated. */
    thread_loop_c (t, domain)
    {
        if (FLUID_THREAD_P(t))
        {
            begin_c_loop_all (c, t)
            {
                C_UDSI(c, t, 1) +=
                K_EL*NV_MAG2(C_UDSI_G(c, t, 0))*C_VOLUME(c, t);
            }
            end_c_loop_all (c, t)
        }
    }
}
```

User Defined Memory (UDM)

- ◆ User-allocated memory
 - Allow users to allocate memory (up to 500 locations) to store and retrieve the values of *field variables* computed by UDF's (for postprocessing and use by other UDFs)
 - Same array dimension and size as any flow variable
 - UDMs are not solved by the solver
 - Number of User-Defined Memory Locations is specified in the User-Defined Memory panel
 - Accessible via macros
 - Cell values: `C_UDMI(c, t, i)`
 - Face values: `F_UDMI(f, t, i)`
 - Saved to FLUENT data file

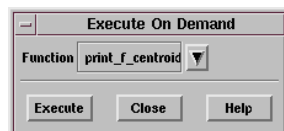


User Defined Memory (2)

```
DEFINE_ON_DEMAND(scaled_temp)
{
    Domain *domain = Get_domain(1);
    /* Compute scaled temperature store in user-defined
       memory */
    thread_loop_c(t,domain)
    {
        begin_c_loop(c,t)
        {
            temp = C_T(c,t);
            C_UDMI(c,t,0)=(temp - tmin)/(tmax-tmin);
        }
        end_c_loop(c,t)
    }
}
```

Execute on Demand

- ◆ This provides a hook to execute any set of calculation or I/O operations at will of the user while the solver is not iterating
- ◆ Executed instantaneously when activated by user
- ◆ Define→User-Defined
→Execute on Demand...



```
extern Domain *domain;
#define SETMIN(a,b)((b)<(a)?(a=b):(a))
#define SETMAX(a,b)((b)>(a)?(a=b):(a))
DEFINE_ON_DEMAND(scaled_temp)
{
    thread_loop_c(t,domain)
    {
        real tmin=-1.e10, tmax=1.e10;
        /* Compute min & max temperature */
        begin_c_loop(c,t)
        {
            SETMIN(tmin,C_T(c,t));
            SETMAX(tmax,C_T(c,t));
        }
        end_c_loop(c,t)
    }
}
```




User Defined Function for Discrete Phase Model

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DPM Macros (1)

- ◆ **Tracked_particle *p** DPM Datatype
- ◆ DPM tracks particles in Lagrangian frame
- ◆ Particle data at current position
 - **P_DIAM(p)** Particle diameter
 - **P_VEL(p) [I]** Particle Velocity
 - **P_T(p)** Particle Temperature
 - **P_RHO(p)** Particle density
 - **P_MASS(p)** Particle mass
 - **P_TIME(p)** Current time for particle
 - **P_DT(p)** Particle time step
 - **P_LF(p)** Particle liquid fraction
 - **P_VFF(p)** Particle volatile fraction

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DPM Macros (2)

- ◆ Values of particle properties at entry to current cell
 - **P_DIAM0(p)** Diameter
 - **P_VEL0(p)[i]** Velocity
 - **P_TO(p)** Temperature
 - **P_RHO0(p)** Density
 - **P_MASS0(p)** Mass
 - **P_TIME0(p)** Time
 - **P_LF0(p)** Liquid fraction
- ◆ Values of particle properties at injection into domain
 - **P_INIT_DIAM(p)** Diameter
 - **P_INIT_MASS(p)** Mass
 - **P_INIT_RHO(p)** Density
 - **P_INIT_TEMP(p)** Temperature
 - **P_INIT_LF(p)** Liquid fraction

DPM Macros (3)

- **P_EVAP_SPECIES_INDEX(p)** Evaporating species index in mixture
- **P_DEVOL_SPECIES_INDEX(p)** Devolatilizing species index in mixture
- **P_OXID_SPECIES_INDEX(p)** Oxidizing species index in mixture
- **P_PROD_SPECIES_INDEX(p)** Combustion product species index in mixture
- **P_CURRENT_LAW(p)** Current law index
- **P_NEXT_LAW(p)** Next particle law index

DPM Macros (4)

◆ Material Properties for particles

➤ P_MATERIAL(p)	Material pointer for particles
➤ DPM_SWELLING_COEFFI(p)	Swell coefficient for devolatilization
➤ DPM_EMISSIVITY(p)	Particle radiation emissivity
➤ DPM_SCATT_FACTOR(p)	Particle radiation scattering factor
➤ DPM_EVAPORATION_TEMPERATURE(p)	Evaporation temperature
➤ DPM_BOILING_TEMPERATURE(p)	Boiling temperature
➤ DPM_LATENT_HEAT(p)	Latent Heat
➤ DPM_HEAT_OF_PYROLYSIS(p)	Heat of pyrolysis
➤ DPM_HEAT_OF_REACTION(p)	Heat of reaction
➤ DPM_VOLATILE_FRACTION(p)	Volatile fraction
➤ DPM_CHAR_REACTION(p)	Char fraction
➤ DPM_SPECIFIC_HEAT(p, t)	Specific Heat at temperature t

DPM Functions (1)

◆ The following functions can be modeled:

- Body force - custom body forces on the particles
- Drag - user defined drag coefficient between particles and fluid
- Source Terms - access particle source terms
- Output - user can modify what is written out to the sampling plane output
- Erosion - called when particle encounters "reflecting" surface
- DPM Law - custom laws for particles
- Scalar Update - allows users to update a scalar every time a particle position is updated
- Switch - change the criteria for switching between laws

DPM Functions (2)

➤ DEFINE_DPM_BODY_FORCE	Body force
➤ DEFINE_DPM_DRAG	Drag
➤ DEFINE_DPM_SOURCE	Source terms
➤ DEFINE_OUTPUT	Output
➤ DEFINE_DPM_LAW	Custom law
➤ DEFINE_DPM_EROSION	Erosion
➤ DEFINE_DPM_INJECTION_INIT	Initialize injections
➤ DEFINE_DPM_SCALAR_UPDATE	Update scalars
➤ DEFINE_DPM_SWITCH	Switch laws

* **Note:** the arguments to these functions are described in the UDF manual posted in http://www.fluentusers.com/fluent6/doc/ori/html/udf/main_pre.htm

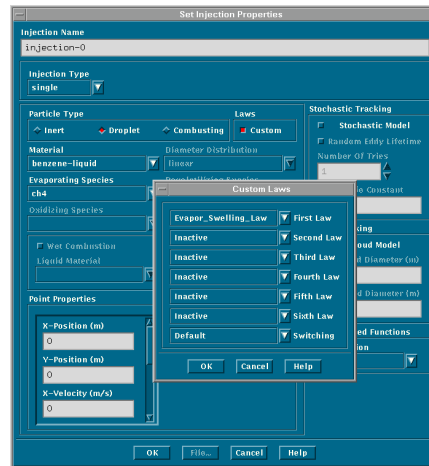
DPM Functions (3)

- ◆ The function shown models a custom law
- ◆ The parameter p is a pointer to data structure of type Tracked Particle

```
#include "udf.h"
#include "dpm.h"
DEFINE_DPM_LAW(Evapor_Swelling_Law, p, ci)
{
    real swelling_coeff = 1.1;
    /* first, call standard evaporation routine to calculate mass and
    heat transfer */
    Vaporization_Law(p);
    /* compute new particle diameter and density */
    P_DIAM(p) = P_INIT_DIAM(p)*(1. + (swelling_coeff - 1.)*
        (P_INIT_MASS(p) P_MASS(p))/
        (DPM_VOLATILE_FRACTION(p)*P_INIT_MASS(p)));
    P_RHO(p) = P_MASS(p) / (3.14159*P_DIAM(p)
        *P_DIAM(p)*P_DIAM(p)/6);
    P_RHO(p) = MAX(0.1, MIN(1e5, P_RHO(p)));
}
```

DPM Functions (4)

- ◆ The law is activated through **Define**→**Models**→**Dispersed Phase**→**Injections...Create**
- ◆ The Set Injections Properties panel comes up where Custom is activated under Laws
- ◆ This brings up the Custom Laws panel where the user can specify the appropriate law





UDFs for Multiphase Flows

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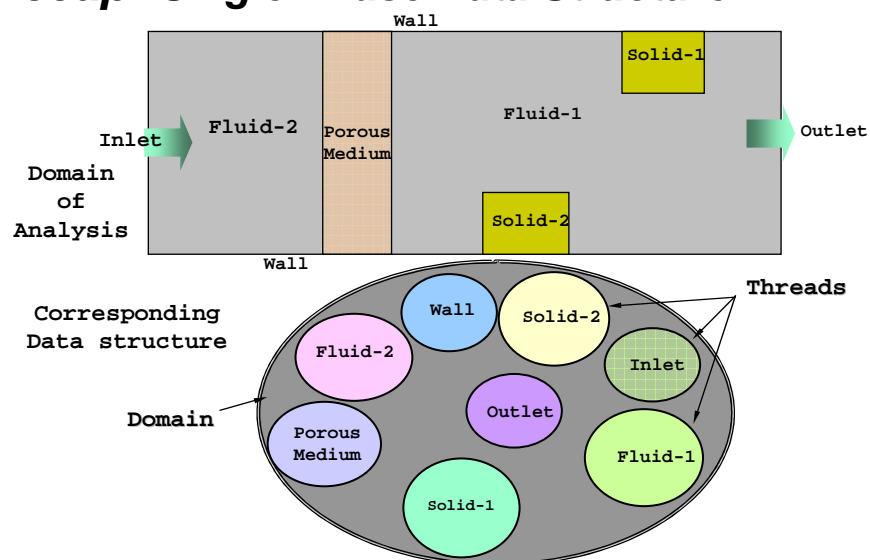
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Recap: Single Phase Data Structure



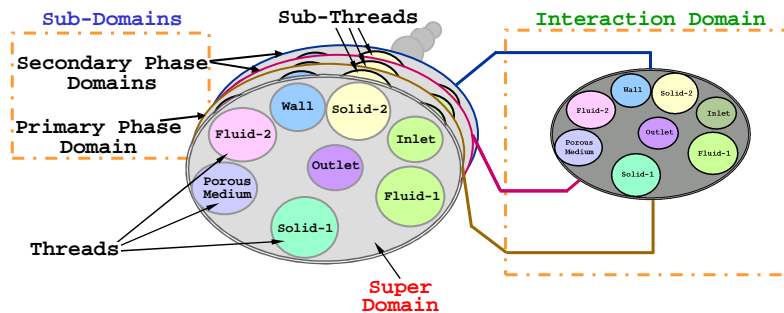
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Data Structure for Multiphase Models

- ◆ Data Structure in multiphase models involve **multiple domains**:
 - **Super Domain**: This is the top-level domain contains all phase-independent and **mixture** data: geometry, connectivity, property
 - **Sub-domains (phase domains)**: Each phase has a sub-domain that inherits the mixture-specific data and maintains the phase-specific data
 - **Interaction Domain**: To activate the phase interaction mechanisms

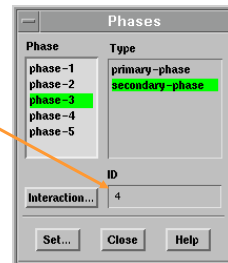


The Threads in Multi-Domains

- ◆ The mixture:
 - In single-phase, a mixture represents the sum over all the **species**
 - In multiphase it represents the sum over all the **phases**
- ◆ This distinction is important
 - Also, the code will later be extended to multiphase multi-component fluids (where, for example, *a phase could be a mixture of species*)
- ◆ Thread data structures:
 - Threads must be associated with the super domain and all sub-domains
 - For each cell (or face) thread of the super domain, there is a corresponding cell (or face) thread for each sub-domain
 - Some of the information defined in one thread of the super domain is shared with the corresponding threads of each of the sub-domains
 - Threads associated with the super domain are referred to as super-threads
 - Threads associated with the subdomain are referred to as phase-level threads or sub-threads

The Domain-Ids and The Thread-Ids

- ◆ For multiphase models, the domains need to be identified by unique Ids (including Interaction domain)
- ◆ **Domain_ID** of the super (mixture) domain is always '1'
- ◆ **Domain_IDs** are **not necessarily ordered** sequentially
- ◆ Therefore, to access the phase domains, each phase also has a **phase_domain_index**:
 - '0' for the primary phase
 - 'N-1' for the last secondary phase
 - **phase_domain_index** is used in UDFs to retrieve phase thread pointers
 - Useful when you want to access data for another phase from an UDF for a particular phase



Domain Looping Macro

- ◆ **sub_domain_loop(subdomain, mixture_domain, phase_index)**
 - Loops over all phases (sub-domains) in a mixture
 - **mixture_domain** is already available
 - **subdomain, phase_index** are defined locally, initialized within the macro
- ◆ An Example for the loop, **Domain_ID** and the **phase_domain_index**:

```
DEFINE_ADJUST(print_id, mix_domain)
{
    Domain *s_d; /*subdomain pointer, locally defined*/
    int p_d; /* loop counter for phase_domain_index, locally defined*/
    int p_d_id; /* mix_domain is available*/
    sub_domain_loop(s_d, mix_domain, p_d)
    {
        p_d_id = DOMAIN_ID(s_d);
        Message("the phase domain id = %d and the phase
                domain index = %d\n", p_d_id, p_d);
    }
}
```


Thread Looping Macro

- ◆ **sub_thread_loop(subthread,mixture_thread,phase_index)**
 - Loops over all threads in a mixture
 - **mixture_thread** is already available
 - **subthread** & **phase_index** are defined locally, initialized within the macro

An Example:

```
/*compute bulk density of mixture and store it in a UDM*/
DEFINE_ADJUST(calc_den, mix_domain)
{
  Thread *mix_thread;
  thread_loop_c(mix_thread,mix_domain)
  {
    cell_t c;
    begin_c_loop(c,mix_thread)
    {
      Thread *s_t;
      int p_d_i;
      C_UDMI(c,mix_thread,0) = 0.;
      sub_thread_loop(s_t, mix_thread, p_d_i)
      C_UDMI(c,mix_thread,0) += C_VOF(c,s_t)*C_R(c,s_t);
    }
    end_c_loop(c,mix_thread)
  }
}
```

Other Looping Macros

- ◆ **mp_thread_loop_c(cell_thread, mixture_domain, pt)**
 - **cell_thread** is a pointer to mixture thread in the **mixture_domain**
 - **mixture_domain** is already assumed to be available
 - **pt** is an array of thread pointers
- ◆ **mp_thread_loop_f(face_threads, mixture_domain, pt)**
 - **face_threads** is a pointer to face thread in the **mixture_domain**
 - **mixture_domain** is already assumed to be available
 - **pt** is an array of thread pointers pointing to the phase-level threads

An Example:

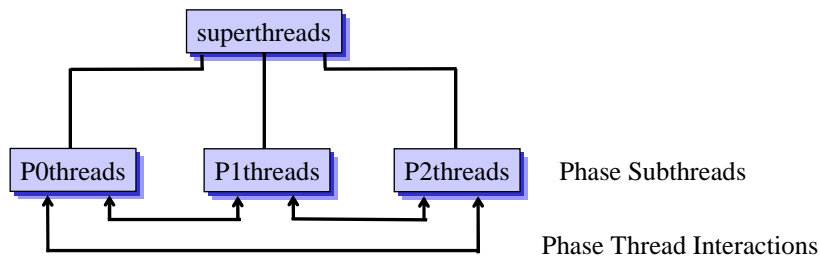
```
DEFINE_ADJUST(print_vof, mix_domain)
{
  Thread *mix_thread;
  Thread **pt;
  mp_thread_loop_c(mix_thread, mix_domain, pt)
  {
    cell_t c;
    begin_c_loop(c, mix_thread)
    {
      Message("cell volume fraction = %f\n",C_VOF(c,pt[0]));
    }
    end_c_loop(c, mix_thread)
  }
}
```

Access the Right Thread / Domain

- ◆ While writing UDF's, it is important that the right thread / domain is accessed
 - **C_R(cell,thread)** will return
 - The mixture density if **thread** is the mixture thread or
 - The phase densities if it is the **phase thread**
- ◆ In general the type of 'DEFINE' macro determines which thread or domain (mixture or phase) gets passed to your UDF
 - **DEFINE_INIT** and **DEFINE_ADJUST** functions always get passed the domain structure associated with the super domain
 - **DEFINE_ON_DEMAND** functions are not passed any domain structures
 - If your UDF is not explicitly passed the pointer to the thread or domain required, then you can use a multiphase-specific utility macro to retrieve it

Superthreads and Phasethreads

- ◆ Each Thread is also in a hierarchy that matches that of the domains
- ◆ The "superthreads" are where the "mixture" of the phases is stored and so are often called the "mixture threads"
- ◆ Shared values such as the cell's geometry data are stored in the superthread
- ◆ Each Phase has its own set of threads known as a "subthreads" or "phase threads"



Access Variables External to a UDF

- ◆ **Get_Domain(Domain-ID)**
 - Usage: `Domain *domain=Get_Domain(n);`
'n' is the **Domain-ID**, as appear in Define-Phase GUI. **It is always '1' for the mixture domain**
- ◆ **DOMAIN_ID(domain)**
 - Usage: `int domain_id = Domain_ID(subdomain);`
'subdomain' is the pointer to a phase-level domain; **domain_id** upon return is the same integer ID displayed in the GUI under Define-Phases panel
- ◆ **DOMAIN_SUB_DOMAIN(mixture_domain,ph_domain_index)**
 - Usage: `Domain *mixture_domain;`
`Domain *subdomain = DOMAIN_SUB_DOMAIN(mixture_domain, phase_domain_index);`
returns the phase pointer subdomain for the **phase_domain_index**

Access Variables External to a UDF (2)

- ◆ **THREAD_SUB_THREAD(mixture_thread,ph_domain_index)**
 - Usage:
`int ph_d_index = 0; /* primary phase index is 0 */`
`Thread *mix_th; /* mixture-level thread pointer */`
`Thread *subth=THREAD_SUB_THREAD(mix_th, ph_d_index);`
returns the phase-level thread pointer for the given **ph_d_index**
- ◆ **THREAD_SUB_THREADS(mixture_thread)**
 - Usage:
`Thread *mixture_thread;`
`Thread **pt; /* initialize pt: pointer array */`
`pt = THREAD_SUB_THREADS(mixture_thread)`
returns the pointer array, **pt**, whose elements contain pointers to phase-level threads (subthreads)

Access Variables External to a UDF (3)

◆ THREAD_SUPER_THREAD(subthread)

➤ Usage:

```
Thread *subthread; /*pointer to a phase thread within the mixture*/  
Thread *mix_thread=THREAD_SUPER_THREAD(subthread)
```

Given a phase thread pointer, it returns the super-thread (mixture-thread) pointer

◆ DOMAIN_SUPER_DOMAIN(subdomain)

➤ Usage:

```
Domain *subdomain; /*pointer to a phase domain within the mixture*/  
Domain *mixture_domain = DOMAIN_SUPER_DOMAIN(subdomain)
```

It returns the mixture domain pointer

Access Variables External to a UDF (4)

◆ PHASE_DOMAIN_INDEX(subdomain)

➤ Usage:

```
Domain *subdomain; /*points to a phase domain within the mixture*/  
int phase_domain_index = PHASE_DOMAIN_INDEX(subdomain)
```

returns the phase domain index for the phase domain (subdomain) pointer;

It is an integer that starts with '0' for the primary phase and is incremented by one for each secondary phase

◆ THREAD_DOMAIN(thread)

➤ Usage:

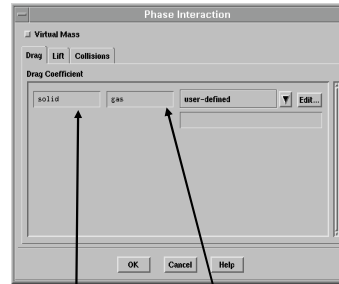
```
Thread *subthread; /*points to a phase thread within the mixture*/  
Thread *mix_thread=THREAD_SUPER_THREAD(subthread)  
Domain *subd=THREAD_DOMAIN(subthread); /*points to a phase domain*/  
Domain *mixd=THREAD_DOMAIN(subthread); /*points to mixture domain*/
```

returns domain pointer for the **thread**

Exchange Macros(1)

◆ **DEFINE_EXCHANGE_PROPERTY**
(name, c, mixture_thread,
second_column_phase_index,
first_column_phase_index)

- This macro is used to specify custom drag & lift coefficients for the Eulerian multiphase model
- **mixture_thread** points to the mixture thread
- **c** is the index of a cell on the **mixture_thread**
- **first_column_phase_index** and **second_column_phase_index** are integer identifiers corresponding to the pair of phases in your multiphase flow
- The identifiers correspond to the phases that are selected in the Phase-Interaction panel in the GUI
- The UDF returns the real value of the lift or drag coefficient



Exchange Macros(2)

◆ **DEFINE_VECTOR_EXCHANGE_PROPERTY(name, c, mixture_thread,
second_column_phase_index, first_column_phase_index,
vector_result)**

- This macro is used to specify custom slip velocities for multiphase Mixture model
- **mixture_thread** points to the mixture thread
- **c** is the index of a cell on the **mixture_thread**
- **first_column_phase_index** and **second_column_phase_index** are integer identifiers corresponding to the pair of phases in your multiphase flow
- The identifiers correspond to the phases that are selected in the **Phase-Interaction** panel in the GUI
- The UDF is passed the real pointer to the slip velocity vector **vector_result**, and it will need to set the components of the slip velocity vector

Exchange Macros(3)

An Example:

```
#include "udf.h"
#include "sg_mphase.h"
DEFINE_VECTOR_EXCHANGE_PROPERTY(custom_slip, c, mixture_thread,
second_column_phase_index, first_column_phase_index, vector_result)
{
    real grav[2] = {0., -9.81};
    real K = 5.e4;
    real pgrad_x, pgrad_y;
    Thread *pt, *st; /* thread pointers for primary & secondary phases*/

    pt = THREAD_SUB_THREAD(mixture_thread, second_column_phase_index);
    st = THREAD_SUB_THREAD(mixture_thread, first_column_phase_index);
    /* Now the threads are known for primary (0) & secondary(1) phases */
    pgrad_x = C_DP(c, mixture_thread)[0];
    pgrad_y = C_DP(c, mixture_thread)[1];
    vector_result[0] = -(pgrad_x/K)+(((C_R(c,st)-C_R(c,pt))/K)*grav[0]);
    vector_result[1] = -(pgrad_y/K)+(((C_R(c,st)-C_R(c,pt))/K)*grav[1]);
}
```

Cavitation Macros

- ◆ **DEFINE_CAVITATION_RATE** (*name,c,t,p,rhoV,rhoL,vofV,p_v,n_b,mdot*)
- ◆ You can use this macro to model the creation of vapor due to pressure tension in a multiphase flow
 - It is applied in the **User-Defined-Function-Hooks→Cavitation-Mass-Rate-Function** panel
 - **t** is a pointer to the mixture-level thread
 - **c** is the index of a cell on the thread pointed to by **t**
 - The remaining arguments are real pointers to the following data:
 - Shared pressure (**p**), vapor density (**rhoV**), liquid density (**rhoL**), vapor volume fraction (**vofV**), vaporization pressure (**p_v**), number of bubbles per unit volume (**n_b**), and rate of vapor formation (**mdot**)
 - The UDF sets the value referenced by the real pointer **mdot**, to the cavitation rate

Miscellaneous: Multiphase Macros

- ◆ Phase diameter
 - `C_PHASE_DIAMETER(c, phase_thread)`
- ◆ Phase Volume-fraction
 - `C_VOF(c, phase_thread)`
- ◆ Phase velocity gradients
 - `C_U_G(c, phase_thread)`
 - `C_V_G(c, phase_thread)`
 - `C_W_G(c, phase_thread)`

Miscellaneous : Multiphase Macros

- ◆ Phase volume fraction gradients: `C_VOF_G(c, phase_thread)`
 - Memory needs to be allocated and gradients need to be explicitly calculated

```
Domain    *pDomain = DOMAIN_SUB_DOMAIN(domain, P_PHASE);
Alloc_Storage_Vars    (pDomain, SV_VOF_RG, SV_VOF_G, SV_NULL);
Scalar_Reconstruction(pDomain, SV_VOF, -1, SV_VOF_RG, NULL);
Scalar_Derivatives    (pDomain, SV_VOF, -1, SV_VOF_G, SV_VOF_RG,
                       Vof_Deriv_Accumulate);
```

Miscellaneous: Multiphase Macros

- ◆ Check if a given thread is a “super” or “sub” thread

THREAD_SUPER_THREAD(thread) is **NULL** for mixture thread,
and not **NULL** for phase threads

- mixture : **if (NULLP (THREAD_SUPER_THREAD(thread)))**
- phase : **if (!NULLP (THREAD_SUPER_THREAD(thread)))**



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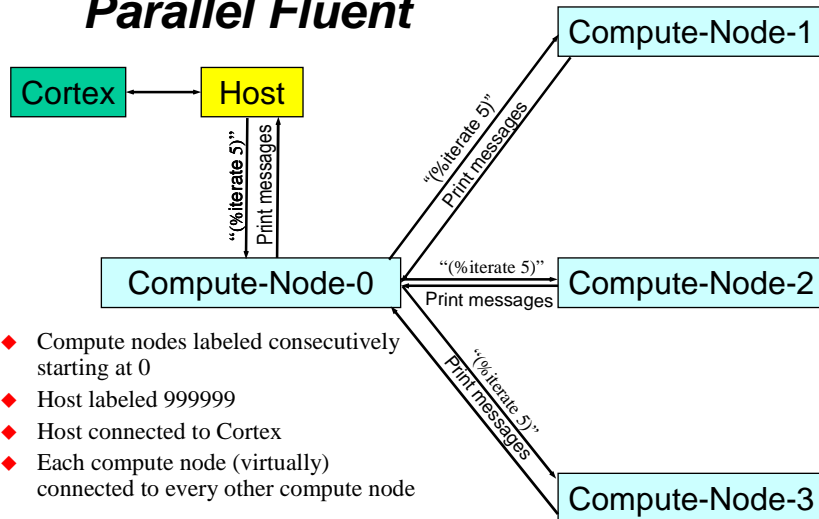
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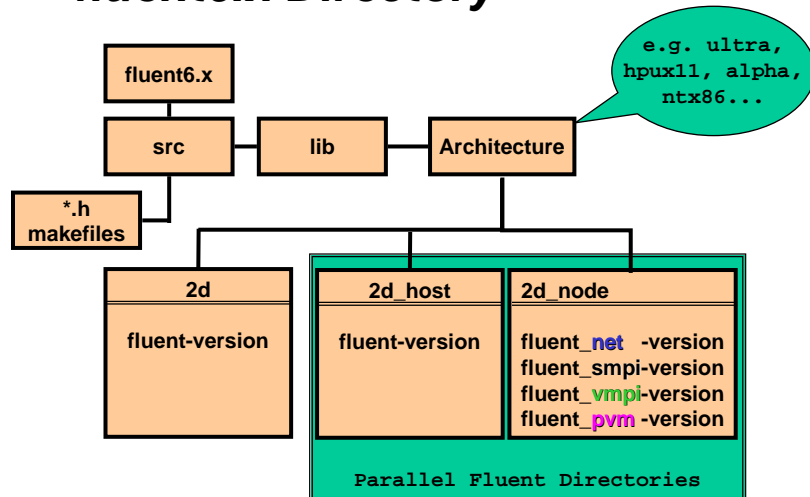


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Intro to Compiler Directives

- ◆ “#if” is a compiler directive (similar to “#define”)
- ◆ A “#endif” is used to close a “#if

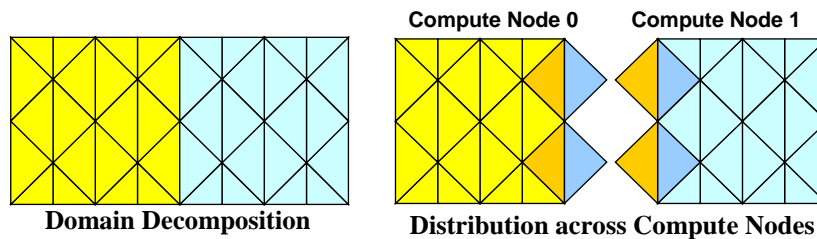
```

#if RP_NODE    /* Compute-Node */
#if RP_HOST    /* Host */
#if PARALLEL   /* Equivalent to #if RP_HOST||RP_NODE*/
#if !PARALLEL  /* Serial */
#if RP_HOST
    Message("I'm the Host process \n");
#endif
#if RP_NODE
    Message("I'm the Node process number:%d \n", myid);
#endif

```

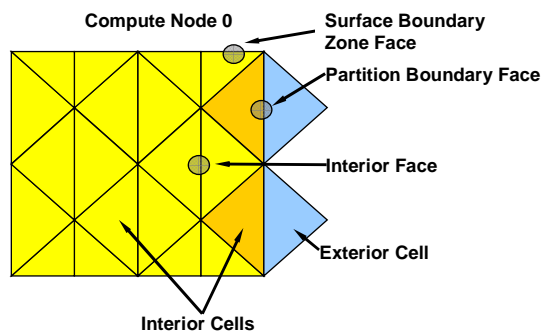
Partitioning (1)

- ◆ Domain Decomposition Technique: Splits the domain across Compute Nodes
- ◆ Because Fluent's algorithms expect a cell to be on both sides of an interior face, copies of the neighboring partition's cells are kept on each Node
- ◆ Compute Node 0 has copies of the cells on the other side of all partition faces and Compute Node 1 has corresponding cell copies from Node 0



Partitioning (2)

The main cells of the partition are designated "Interior" cells and the additional copied cells from other Compute Nodes are designated "Exterior" cells
The Partition Boundary Faces are a special type of Interior face



Partitioned Thread Loop (1)

```
begin_c_loop(c,t)
{
}
end_c_loop(c,t)
```

- ◆ In parallel use, above loop construct loops through the Exterior cells too
- ◆ Use `begin_c_loop_int(c,t)` in all UDFs that are to be parallelized:

```
begin_c_loop_int(c,t)
{
}
end_c_loop_int(c,t)
```

- ◆ This loop excludes the exterior cells to replicate serial `begin_c_loop(c,t)`
- ◆ Another loop construct loops through the exterior cells only :

```
begin_c_loop_ext(c,t)
{
}
end_c_loop_ext(c,t)
```

- ◆ It is rarely used in UDFs and does nothing if compiled in serial version

Partitioned Thread Loop (2)

- ◆ Similar loops exist for faces:

```
begin_f_loop_all(f,t)
{...}
end_f_loop_all(f,t)
```

```
begin_f_loop_int(f,t)
{...}
end_f_loop_int(f,t)
```

- ◆ But you can simply use the standard loop and check to see if the face is "allocated" to this Thread using:

```
begin_f_loop (f,t)
{
  if (PRINCIPAL_FACE_P(f,t))
  {...}
}
end_f_loop(f,t)
```

Inter-Process Communication (1)

- Each compute node maintain local cache of individual variables
- Synchronization or make global reduction of such data involves communication in a particular order
- Consider the simple operation of passing a user defined cortex parameter that is set using scheme but is used in a UDF

Serial Code

```
DEFINE_INIT(set_temp, domain)
{
    real i_temp;
    i_temp = RP_Get_Real("user-temp");
    begin_c_loop(c,t)
        C_T(c,t)=i_temp;
    end_c_loop(c,t)
}
```

Combined (Serial & Parallel) Code

```
DEFINE_INIT(set_temp, domain)
{
    real i_temp;
    #if !RP_NODE /* i.e. serial or host */
        i_temp = RP_Get_Real("user-temp");
    #endif
    host_to_node_real_1(i_temp);
    #if !RP_HOST /* i.e. serial or node */
        begin_c_loop_int(c,t)
            C_T(c,t)= i_temp;
        end_c_loop_int(c,t)
    #endif
}
```

Inter-Process Communication (2)

- To ensure same code to work for serial and parallel versions, negated compiler directives are mostly used:

```
#if !RP_NODE /* i.e. serial or host */
#if !RP_HOST /* i.e. serial or node */
#if !PARALLEL /* i.e. serial only */
```

- The macro "host_to_node_real_1(i_temp);" is defined as a **Send** command in the Host version, a **Receive** command in the Compute Node versions and does **Nothing** in the Serial version
- The reciprocal command to host_to_node_real_1() is node_to_host_real_1();
- But this only sends the value of temp from Node0 to the Host
- The formal broadcasting and host communication can be done as below:

```
temp = PRF_GRSUM1(temp); /*This sums up temp over all nodes*/
/*All nodes now have temp=sum */
node_to_host_real_1(temp);/*only Node0 sends data to Host */
```

Global Reduction

This combination process is called “Reduction” and there are a number of ways to reduce your data depending on what you want:

- 1) If you want the total value over all the Nodes, you use a Summation Reduction
- 2) If you want the Max or Min over all the Nodes use a High or Low Reduction
- 3) If you want a logical test over all nodes use an And or Or Reduction

There are different macros depending on what data type you’re sending:

```
count      = PRF_GISUM1(count);    /* Total Integer count */
min_temp = PRF_GRLOW1(min_temp); /* Global minimum */
PRF_GLOR(sonic_tests, 3, work); /* Arrays can be reduced too,
                                needs a work array */
PRF_GRSUM4(v_x,v_y,v_z,v_mag); /* 4 vars are reduced at a time */
```

Example UDF (1)

- Find totals and averages of a property over all the cells
- Purpose is to write an UDF that works for both Parallel and Serial solvers

```
#include "udf.h"
DEFINE_ON_DEMAND(av_pres_in_thread)
{int thread_id;
 real vol_sum=0.0, pres_sum=0.0;
#if !RP_HOST                                /* serial or node */
    cell_t c; Thread *t;
#endif /* !RP_HOST */
#if !RP_NODE                                /* serial or host */
    thread_id=RP_Get_Integer("udf/av_thread_id");
#endif /* !RP_NODE */
    host_to_node_int_1(thread_id);          /* Passes on serial */
#if !RP_HOST                                /* serial or node */
    t= Lookup_Thread(Get_Domain(1), thread_id);
    begin_c_loop_int(c,t)                  /* Internal cells only*/
    {vol_sum += C_VOLUME(c,t);
     pres_sum += C_P(c,t) * C_VOLUME(c,t);}
    end_c_loop_int(c,t)
#endif /* !RP_HOST */                      /* Continued */
```

Example UDF (2)

```
#if RP_NODE
    Message("Sub totals on Node %d: %f,%f\n",myid ,
            pres_sum ,vol_sum);
#endif /* RP_NODE */
    vol_sum = PRF_GRSUM1(vol_sum);
    pres_sum = PRF_GRSUM1(pres_sum);
#if RP_NODE
    Message("Reduced vals Node %d: %f,%f\n",myid ,
            pres_sum ,vol_sum);
#endif /* RP_NODE */
node_to_host_real_2(vol_sum,pres_sum);
#if !RP_NODE /* i.e., host or serial*/
    Message("Avg. pressure over Thread %d is %f Pa\n", thread_id,
            pres_sum/vol_sum);
#endif /* !RP_NODE */
}
```

Message0 ()

- A function that can be run on node0 that prints directly to the cortex window
- Also works for serial processes

```
Message0("Average pressure over Thread %d ",thread_id);
Message0("is %f Pa\n",pres_sum/vol_sum);
```

- Note the exact similarity of the function “Message0” with Message and printf commands

Parallel File Output

- ◆ In a parallel session, file I/O can be done only through the **Node_Zero**

Example:

```
#if PARALLEL
if (I_AM_NODE_ZERO_P)
{ sprintf (ntim,"outfile-%d", ntime);
  if (fd == NULL) /*Open a new file */
    {fd = fopen(ntim,"w");}
  /* if new file "open" failed, try to append */
  if (fd == NULL) /* reopen the file in append-mode*/
    {fd = fopen(ntim,"a");
     Message( "Appending to existing file: %s", ntim);
     fprintf(fd,"\nAppend begins at: %f \n", f_time);}
}
#endif
```




Miscellaneous Functions/Macros

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Trigonometric Functions

- | | |
|---|-------------------------------------|
| ◆ <code>double acos (double x);</code> | returns the arc-cosine of x |
| ◆ <code>double asin (double x);</code> | returns the arc-sine of x |
| ◆ <code>double atan (double x);</code> | returns the arc-tangent of x |
| ◆ <code>double atan2 (double x, double y);</code> | returns the arc-tangent of x/y |
| ◆ <code>double cos (double x);</code> | returns the cosine of x |
| ◆ <code>double sin (double x);</code> | returns the sine of x |
| ◆ <code>double tan (double x);</code> | returns the tangent of x |
| ◆ <code>double cosh (double x);</code> | returns the hyperbolic cosine of x |
| ◆ <code>double sinh (double x);</code> | returns the hyperbolic sine of x |
| ◆ <code>double tanh (double x);</code> | returns the hyperbolic tangent of x |

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Miscellaneous Math-Functions

- ◆ `double sqrt (double x);` returns the square root of x
- ◆ `double pow (double x, double y);` returns x^y
- ◆ `double exp (double x);` returns e^x
- ◆ `double log (double x);` returns $\ln(x)$
- ◆ `double log10 (double x);` returns $\ln_{10}(x)$
- ◆ `double fabs (double x);` returns $|x|$
- ◆ `double ceil (double x);` smallest integer not less than x
- ◆ `double floor (double x);` largest integer not greater than x
- ◆ The macro **UNIVERSAL_GAS_CONSTANT** returns the value of the universal gas constant (8314.34), which is expressed in SI units of J/Kmol-K
- ◆ The macro **M_PI** returns the value of π

Standard I/O Functions

- ◆ use **Message** instead of **printf** in compiled UDFs (UNIX only)
`Message ("Volume integral: %g\n", sum_vol);`
- ◆ `FILE *fopen(char *filename, char *type);` opens a file
- ◆ `int fclose(FILE *fd);` closes a file
- ◆ `int fprintf(FILE *fd, char *format, ...);` formatted print to a file
- ◆ `int printf(char, *format, ...);` print to screen
- ◆ `int fscanf(FILE *fd, char *format, ...);` formatted read from a file

See your system manual pages for more details
Note that for parallel runs, the I/O macros need to be different

- ◆ Example:
`FILE *fd;
real f1, f2;
fd = fopen("data.txt", "r");
fscanf(fd, "%f %f", &f1, &f2);
fclose(fd);`

Special Macro's

- ◆ `cxboolean Data_Valid_P()` Equals 1 if data is available,
0 if not
Usage: `if(!Data_Valid_P())return;`
- ◆ `cxboolean FLUID_THREAD_P(t0)` true if thread t0 fluid thread
- ◆ `cxboolean SOLID_THREAD_P(t0)` true if thread t0 is solid thread
- ◆ `cxboolean BOUNDARY_FACE_THREAD_P(t0)` true if thread t0 is boundary thread
- ◆ `NULLP(T_STORAGE_R_NV(t0, SV_UDSI_G(p1)))`
- Checks for storage allocation of user defined scalars
- ◆ `CURRENT_TIME` Real current flow time (in seconds)
- ◆ `CURRENT_TIMESTEP` Real current physical time step size (in sec)
- ◆ `PREVIOUS_TIME` Real previous flow time (in seconds)
- ◆ `PREVIOUS_2_TIME` Real flow time two steps back in time (in sec)
- ◆ `N_TIME` Integer number of time steps
- ◆ `N_ITER` Integer number of iterations

Miscellaneous: Vector Utilities

- ◆ `ND_ND` in the declaration of a vector or matrix stands for the actual fluent dimension (2D / 3D)
- ◆ `X[ND_ND]` is equivalent to:
 - 2D: `x[2]`
 - 3D: `x[3]`
- ◆ `NV_MAG` computes the magnitude of a vector: `X[ND_ND]`
- ◆ `NV_MAG(x)` is equivalent to:
 - 2D: `sqrt(x[0]*x[0] + x[1]*x[1]);`
 - 3D: `sqrt(x[0]*x[0] + x[1]*x[1] + x[2]*x[2]);`
- ◆ `NV_MAG2` computes the sum of squares of vector components
- ◆ `NV_MAG2(x)` is equivalent to:
 - 2D: `(x[0]*x[0] + x[1]*x[1]);`
 - 3D: `(x[0]*x[0] + x[1]*x[1] + x[2]*x[2]);`

Miscellaneous: Vector Utilities

- ◆ **ND_SUM** computes the sum of **ND_ND** arguments
- ◆ **ND_SUM(x,y,z)** is equivalent to:
 - 2D: $\mathbf{x} + \mathbf{y}$;
 - 3D: $\mathbf{x} + \mathbf{y} + \mathbf{z}$;
- ◆ **ND_SET** generates **ND_ND** assignment statements
 - 2D: **ND_SET(u,v,C_U(c,t),C_V(c,t))** is equivalent to:
 - $\mathbf{u} = \mathbf{C_U}(\mathbf{c}, \mathbf{t})$;
 - $\mathbf{v} = \mathbf{C_V}(\mathbf{c}, \mathbf{t})$;
 - 3D: **ND_SET(u,v,w,C_U(c,t),C_V(c,t),C_W(c,t))** is equivalent to:
 - $\mathbf{u} = \mathbf{C_U}(\mathbf{c}, \mathbf{t})$;
 - $\mathbf{v} = \mathbf{C_V}(\mathbf{c}, \mathbf{t})$;
 - $\mathbf{w} = \mathbf{C_W}(\mathbf{c}, \mathbf{t})$;

Miscellaneous: Vector Utilities

- ◆ **NV_V** performs an operation on two vectors
 - **NV_V(a, =, x);**
 - $\mathbf{a}[0] = \mathbf{x}[0]$; $\mathbf{a}[1] = \mathbf{x}[1]$; etc.
 - Note that if you use $\mathbf{a}[0] += \mathbf{x}[0]$; etc.
- ◆ **NV_VV** is a vector operator . The operation that is performed on the elements depends upon what is used as an argument in place of the + signs
 - **NV_VV(a, =, x, +, y)**/* The '+' symbol can be replaced by (-,/,*) */
 - 2D: $\mathbf{a}[0] = \mathbf{x}[0] + \mathbf{y}[0]$, $\mathbf{a}[1] = \mathbf{x}[1] + \mathbf{y}[1]$;
 - 3D: $\mathbf{a}[0] = \mathbf{x}[0] + \mathbf{y}[0]$, $\mathbf{a}[1] = \mathbf{x}[1] + \mathbf{y}[1]$, $\mathbf{a}[2] = \mathbf{x}[2] + \mathbf{y}[2]$;

Miscellaneous: Vector Utilities

- ◆ **NV_V_VS** adds a vector to another which is multiplied by a scalar
 - **NV_V_VS(a,=, x,+,y,*,0.5);**
 - 2D: **a[0]=x[0]+(y[0]*0.5), a[1]=x[1]+(y[1]*0.5);**
 - Note that + sign can be replaced by -, /, or *, and '**' sign can be replaced by '/'
- ◆ **NV_VS_VS** adds a vector to another which are each multiplied by a scalar
 - **NV_VS_VS(a,=,x,*,2.0,+,y,*,0.5);**
 - 2D: **a[0]=(x[0]*2.0)+(y[0]*0.5),**
a[1]=(x[1]*2.0)+(y[1]*0.5);
 - Note that + sign can be used in place of -, *, or /, and '**' sign can be replaced by '/'

Miscellaneous: Vector Utilities

- ◆ The dot products of two sets of vector or components
- ◆ **ND_DOT(x,y,z,u,v,w)** is equivalent to:
 - 2D: **(x*u+y*v);**
 - 3D: **(x*u+y*v+z*w);**
- ◆ **NV_DOT(x,u)** is equivalent to:
 - 2D: **(x[0]*u[0]+x[1]*u[1]);**
 - 3D: **(x[0]*u[0]+x[1]*u[1]+x[2]*u[2]);**
- ◆ **NVD_DOT(x,u,v,w)** is equivalent to:
 - 2D: **(x[0]*u+x[1]*v);**
 - 3D: **(x[0]*u+x[1]*v+x[2]*w);**
- ◆ **NV_CROSS(a,x,y)** is available for 3D only:
 - It returns the cross product of vectors **x** and **y** in the new vector **a**

Closure

- ◆ All UDF-s must be written in SI units
- ◆ UDF-s open up a virtually endless opportunity to extend the modeling capabilities of the basic FLUENT code
- ◆ Details of the examples and all working macros & parameters are available in the UDF manual at Fluent User Services Center



User-Defined Functions Appendix: C-Programming

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C and UDF

- ◆ Many UDFs can be written and used with some limited knowledge of 'C'
- ◆ This presentation will introduce only essential syntax and aspects
- ◆ In general, Macros (hook-ups) are available for accessing various locations in the code during the iterations
- ◆ FLUENT has a large number of internal macro-s and variables that are not accessible from UDFs (Primarily due to copyright reasons)
- ◆ It is advisable to check with your support engineer about the general concept/task that you want to model using UDF
- ◆ More elaborate knowledge of 'C' helps reducing UDF development and debugging time but need not necessarily provide any extended capabilities

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A Brief Introduction to 'C'

- C functions
- C data types
- Pointers and arrays
- Expressions and statements
- C arithmetic and logical operators
- Control flow
- C preprocessor directives

The Basic Form of a C Function

```

/*A simple C function*/ /* Comments are delineated by the character sequence */
/* comments can be placed anywhere in a C listing */
/* use comments liberally to document your UDFs */
#include "udf.h" /* A preprocessor directive for including files */
#define PI 3.14159 /* A preprocessor directive for macro substitution */
real a = 1.2345; /* Global scope: variables defined outside the function body for use
by all functions which follow the definition */
int my-function(int x) /* Function declaration (integer type) */
{ /* C functions are enclosed by curly braces ({...}) */
/* All C statements must end with a semicolon (;) */
    int y,z; /* Local scope: Declare data type for variables y, z variables
defined within the function body are local to the function */
    y = 11; /* Set y = 11 */
    z = a*(x+y)*PI; /* Compute z */
    printf("z = %d",z); /* Print output to screen */
    return z; /* Return integer value */
} /* Right curly brace closes body of function */

```

- ◆ If a function is defined with a specific type, it should return a value of the same type (using the return statement)

Compilers

- ◆ C compilers include a library of standard math, I/O, and utility functions which can be used in your C code
- ◆ Common I/O functions
 - `scanf (...)` - formatted read (like FORTRAN READ)
 - `printf(...)` - formatted print (like FORTRAN WRITE)
- ◆ Common math functions
 - `sin (x)` - sine function
 - `cos (x)` - cosine function
 - `exp (x)` - exponential function
 - `sqrt(x)` - square root function
- ◆ For the UDF compiler, all of the standard functions are defined in the file `udf.h`
 - **NOTE:** *you do not need a copy of `udf.h` when you compile your UDF; the solver gets this from the `Fluent.Inc/fluent6.x/src/` directory*

Comparison with FORTRAN

- ◆ C functions are similar to FORTRAN function subroutines

```
/*A simple C function*/
int myfunction(int x)
{
  int y,z;
  y = 11;
  z = x+y;
  printf("z = %d",z);
  return z;
}
```

```
C An equivalent FORTRAN function
INTEGER FUNCTION MYFUNCTION(X)

  INTEGER X,Y,Z
  Y = 11
  Z = X+Y
  WRITE (*,100) Z
  MYFUNCTION = Z
100 FORMAT("Z = ",I5)
END
```

C Data Types (1)

- ◆ The UDF interpreter supports standard C data types
 - `int, long` - integer data types
 - `float, double, real` - floating point (real) data types
 - `char` - character data type
- ◆ Functions which do not return values are given the type `void`
`void myfunction(int x) {...} /*No return needed*/`
- ◆ You can convert from one type to another by “casting”
 - a cast is denoted by `(type)` where the type is `int`, `float`, etc.

```
int x = 1;  
float y = 3.14159;  
int z = x+((int) y); /*z = 4*/
```

C Data Types (2)

- ◆ C also allows you to create “user-defined” types using `typedef`

```
typedef struct list {    int a;  
                        float b;  
                        int c;};  
typedef struct list mylist; /* mylist is of type structure list*/  
mylist x,y,z; /* x,y,z are “struct list” type */
```

Pointers

- ◆ A pointer is a variable which contains the address of another variable
- ◆ Pointers are defined using the * notation
- ◆ We can make a pointer variable point to the address of predefined variable as follows

```
int *ip; /* a pointer to an integer variable */  
int a=1;  
int *ip;  
ip = &a; /* &a returns the address of variable a */  
printf("content of address pointed to by ip = %d\n", *ip);
```

content of address pointed to by ip = 1

- ◆ Pointers can also point to the beginning of an array (and thus pointers are strongly connected to arrays in C)

Arrays

- ◆ Arrays of variables can be defined using the notation **name[size]** where **name** is the variable name and **size** is an integer which defines the number of elements in the array
- ◆ Some examples

```
int a[10];  
float radii[5];  
a[0] = 1;  
radii[4] = 3.14159265;
```

- ◆ Notes about C arrays
 - The index of C arrays start at 0

Expressions and Statements

- ◆ Arithmetic expressions in C look much like FORTRAN

```
a = 1+(b-c)*d/4;  
pi = 3.141592654;  
area = pi*radius*radius;
```

- ◆ Functions which return values can be used in assignment statements

```
b = myfunc(a); /* Function myfunc() is defined elsewhere */  
c = pow(x,y); /* pow(x,y) returns x raised to power y */
```

- ◆ Functions can also be called without assignments

```
do-stuff(); /* Function do-stuff() takes no arguments */  
printf("x= %f\n",x); /* printf(..) is a standard C library function */
```

Common C Operators

- ◆ Arithmetic operators

```
= assignment  
+ addition  
- subtraction  
* multiplication  
/ division  
% modulo  
++ increment  
-- decrement
```

- ◆ Logical operators

```
< less than  
<= less than or equal to  
> greater than  
>= greater than or equal to  
== equal to  
!= not equal to
```

Control Flow - “If” and “If-else” Statements

◆ ‘if’ and ‘if-else’ statements

```
if (logical-expression)
{statements}
```

```
if (logical-expression)
{statements}
```

```
else
{statements}
```

◆ Example

```
/* C code */
if (q != 1) {a = 0; b = 1;}
if (x < 0.)
    y = x/50.;
else
    y = x/25.;
```

C Equivalent FORTRAN code

```
IF (X.LT.0.) THEN
    Y = X/50.
ELSE
    Y = X/25.
ENDIF
```

Control Flow - “For” Loops

```
for (begin ; end ; increment)
{statements}
```

where:

begin = expression, executed at beginning of loop

end = logical expression to test for loop termination

increment = expression which is executed at the end of each loop iteration (usually incrementing a counter)

Example:

```
/* C code:
Print integers 1-10 and
their squares */
int i, j, n = 10;
for (i = 1 ; i <= n ; i++)
{ j = i*i;
printf("%d %d\n",i,j);
}
```

C Equivalent FORTRAN code

```
INTEGER I,J
N = 10
DO I = 1,10
    J = I*I
    WRITE (*,*) I,J
ENDDO
```

The C Preprocessor

- ◆ The UDF interpreter supports C preprocessor directives
- ◆ Macro substitutions using: **#define name replacement**

```
#define RAD 1.2345  
#define Area_Rectangle(x,y) x*y
```

 - The preprocessor simply substitutes the characters of name with those of replacement
- ◆ File inclusion using the directive **#include**

```
#include "udf.h"  
#include "mystuff.h"
```

 - The files named in quotes must reside in your current directory (except for udf.h which is read automatically by the solver as noted earlier)

Exploring C Further

- ◆ Some topics not discussed here
 - while and do-while control statements
 - structures and unions
 - recursion
 - reading and writing files
 - many details!
- ◆ For more information on C programming, you may consult any general text (there are many available)
A good choice is

The C Programming Language, 2nd Ed.
by Brian Kernighan and Dennis Ritchie
Prentice-Hall, 1988



User-Defined Functions Appendix II: More on C-Programming

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Introduction to C

- ◆ Why write in C?
- ◆ Topics covered in this brief introduction
 - C functions
 - C data types
 - Pointers, arrays & structures
 - Expressions and statements
 - C arithmetic and logical operators
 - Flow control
 - File I/O
 - C preprocessor

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Why C?

- ◆ The FLUENT solver is written in C
- ◆ C is a versatile language with many versatile features
- ◆ Current UDF internal compiler supports only a subset of ANSI C

C Functions (1)

- ◆ The basic form of a C function:

<code>/* A simple C function */</code>	A comment line
<code>#include "udf.h"</code>	A preprocessor directive for including files
<code>#define PI 3.14159</code>	A preprocessor directive for macro substitution
<code>float a = 1.2345;</code>	A variable with "global" scope, outside of {}
<code>float myfunction(int x)</code>	Function declaration (returns a float type)
<code>{</code>	Left curly brace opens body of function
<code>int y;</code>	Variable declarations
<code>float z;</code>	
<code>y = 11;</code>	Set y = 11
<code>z = a*(x+y)*PI;</code>	Compute z
<code>printf("Value is %f",z);</code>	Print z to screen
<code>return z;</code>	Return float value
<code>}</code>	Right curly brace closes body of function

C Functions (2)

- ◆ All C statements must end with a semicolon (;)
- ◆ Comments are delineated by the character sequence
/* . . . */
 - comments can be placed anywhere in a C listing
 - use comments liberally to document your UDFs
- ◆ Groups of C statements are enclosed by curly braces { }

C Functions (3)

- ◆ Variables defined within a { } body are local to that group (local scope)
- ◆ Variables defined outside the function body can be used by all functions which follow the definition (global scope)
- ◆ If a function is defined with a specific type, it must return a value of the same type (using the return statement). If it doesn't return a value, it must be declared void

C Functions (4)

- ◆ C compilers include a library of standard math, I/O, and utility functions which can be used in your C code
- ◆ Some common I/O functions
 - **scanf(...)** - formatted read (like FORTRAN READ)
 - **printf(...)** - formatted print (like FORTRAN WRITE)
- ◆ Some common mathematical functions
 - **sin(x)** - sine function
 - **cos(x)** - cosine function
 - **exp(x)** - exponential function
 - **sqrt(x)** - square root function

Comparison with FORTRAN

- ◆ C functions are similar to FORTRAN function subroutines

```
/* A simple C function */
int myfunction(int x)
{
    int y,z;
    y = 11;
    z = x+y;
    printf("z = %d",z);
    return z;
}
```

```
C An equivalent FORTRAN function
      INTEGER FUNCTION MYFUNCTION(X)
      INTEGER X,Y,Z
      Y = 11
      Z = X+Y
      WRITE (*,100) Z
      MYFUNCTION = Z
100   FORMAT("Z = ",I5)
      END
```

The main() function

- ◆ You won't see it much with UDFs but there is a wrapper function called **main()**
- ◆ Generally a portal in the same way **PROGRAM** was in FORTRAN

```
#include <stdio.h>
int main(void )
{
    printf("Hello, world\n");
    return 0;
}
```

Exercise: Hello, world

- ◆ Start up the editor **gedit** or **emacs**
- ◆ Type in the program from the previous slide
- ◆ Save the file as **hello.c**
- ◆ Compile the program
 - **cc hello.c -o hello**
- ◆ Run the program
 - **./hello**

C Data Types (1)

- ◆ The UDF compiler supports standard C data types
 - `int, long` - integer data types
 - `float, double` - floating point data types (Usually use `real` in UDFs)
 - `char` - character data type
- ◆ Functions which do not return values are given the type `void`
 - `void myfunction(int x) { ... } /* No return needed */`

C Data Types (2)

- ◆ You can convert from one type to another by “casting”

```
int z, x = 10;  
float y = 3.14159;  
z = (int)(x*y); /* z = 31 */
```

- ◆ C also allows you to create “user-defined” types using `typedef`

```
typedef int mytype; /* define mytype to be integer type */  
mytype a, b, c; /* equivalent to int a, b, c */  
typedef float real; /* or double depending on version*/
```

Pointers (1)

- ◆ A pointer is a variable which contains the address of another variable
- ◆ Possibly the greatest leap of faith required for the FORTRAN77 programmer
- ◆ When we declare a variable
 - `int k;`
 - on seeing `int` the compiler sets aside 4 bytes of memory to hold the value of the integer
- ◆ In C, `k` is called an object. Later if we write
 - `k = 2;`
 - the value 2 will be placed at the memory location associated with the object `k`

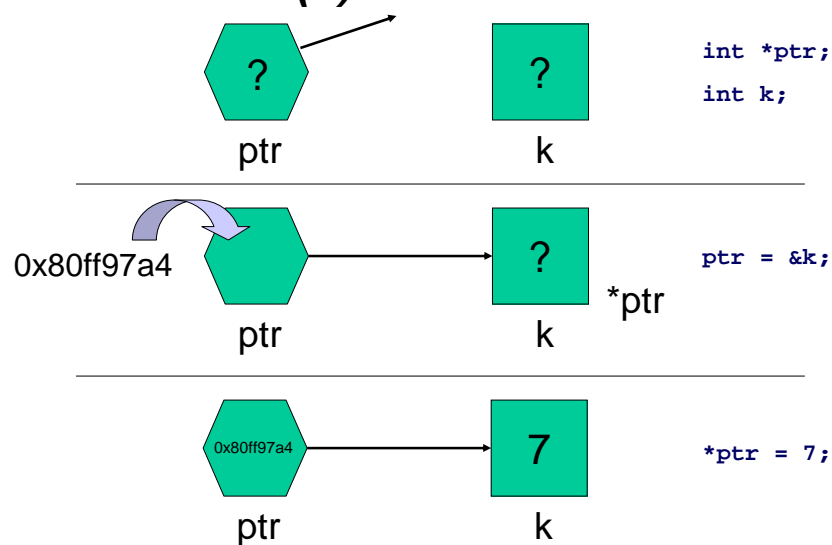
Pointers (2)

- ◆ Suppose we want a variable that holds a memory location (or *address*)
- ◆ Such a variable is called a *pointer*
- ◆ Consider the declaration
 - `int *ptr;`
- ◆ The `*` informs the compiler we wish to set aside enough memory for an address
- ◆ The `int` informs the compiler we wish to store the address of an integer

Pointers (3)

- ◆ Suppose we store the address of our integer `k` in `ptr`
 - `ptr = &k;`
- ◆ Now `ptr` is said to *point to* `k`
- ◆ Suppose we want to copy 7 to the address pointed to by `ptr`
 - `*ptr = 7; /* Contents of ptr = 7 */`
- ◆ The `*` is the *dereferencing operator*
 - It allows access to the value stored at the address `ptr`
- ◆ Since `ptr` points to `k`, we have also set the value of `k` to 7

Pointers (4)



Pointer Fun with **Binky**



by Nick Parlante

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Carpe Post Meridiem!

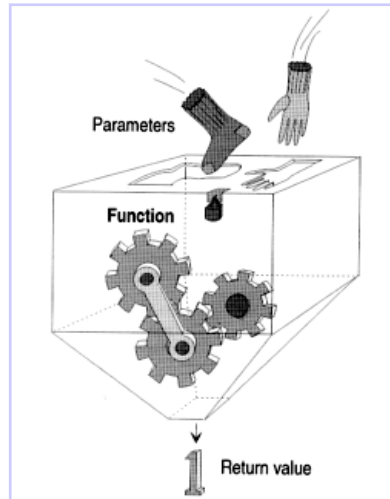
Exercise: Pointer1

- ◆ Save as pointer1.c, compile and execute it

```
#include <stdio.h>
int j, k;
int *ptr;
int main(void)
{
    j = 1;
    k = 2;
    ptr = &k;
    printf("\n");
    printf("j has the value %d and is stored at %p\n", j, (void *)&j);
    printf("k has the value %d and is stored at %p\n", k, (void *)&k);
    printf("ptr has the value %p and is stored at %p\n", ptr, (void *)&ptr);
    printf("The value of the integer pointed to by ptr is %d\n", *ptr);
    return 0;
}
```

Pointers (5)

- In C, function parameters are passed by value
- They only go one way
- You cannot alter the value of a parameter within a function and expect the calling function to see the change
 - Complete opposite of F77
- Only one value is returned by the function
- Classic opportunity to use pointers!!!!



Exercise: By value

```
#include <stdio.h>
#include <math.h>

int main(void)
{
    double x[3] = {1.0, 1.0, 2.0};
    double mag;

    double unit_vector(double *v); /* Function prototype */

    printf("Initial vector: (%9.2e%9.2e%9.2e )\n",x[0],x[1],x[2]);

    mag = unit_vector(x);

    printf("Magnitude of vector: %9.2e\n",mag);

    printf("Unit vector: (%9.2e%9.2e%9.2e )\n",x[0],x[1],x[2]);

}
```


Exercise: By value (cont.)

```
double unit_vector(double *v)
{
    double magnitude;

    magnitude = sqrt(v[0]*v[0]+v[1]*v[1]+v[2]*v[2]);

    v[0] = v[0]/magnitude;
    v[1] = v[1]/magnitude;
    v[2] = v[2]/magnitude;

    return (magnitude);
}
```

- Type this in and compile using
`cc by_value.c -lm -o by_value`
- Look at the output and convince yourself that the by reference route works

Arrays (1)

- ◆ Arrays are defined using the notation:
 - `type name[size];`where `type` is `int`, `float`, etc.; `name` is self-explanatory; and `size` is the number of elements in the array
- ◆ Examples:
 - `int a[10];`
 - `float radii[5];`
- ◆ In C, arrays start with index 0
 - `a[0] = 1; to a[9] = 44;`

Arrays (2)

- ◆ An alternative way of declaring and initialising an array in one go:
 - `int array[] = { 1, 2, 5, 7, 11, 13};`
will create an array with six elements
- ◆ The six integers are located contiguously in memory
 - There is an interesting (and useful) relationship between arrays and pointers

Arrays and Pointers (1)

- ◆ We can access the elements of `array` using pointers

```
int *ptr;
ptr = &array[0];
```
- ◆ `ptr` is set to the address of the zeroth element in the array
 - More simply done by `ptr = array;`
- ◆ We can access the i^{th} element of the array as
 - `*(ptr+i)`

Exercise: Pointer2

- ◆ Save as pointer2.c, compile and execute it

```
#include <stdio.h>
int array[] = {1, 23, 17, 4, -5, 100};
int *ptr;
int main(void)
{
    int i;
    ptr = &array[0]; /* Pointer points to first element of array */

    printf("\n\n");
    for (i=0; i<6; i++)
    {
        printf("array[%d] = %3d    ", i, array[i]);
        printf("ptr + %d = %3d\n", i, *(ptr+i));
    }
    return 0;
}
```

Exercise: Pointer 2 (cont.)

- ◆ Modify the program by changing

```
ptr = &array[0];
```

to

```
ptr = array;
```

and verify that the results are the same

Structures (1)

- ◆ A structure is a user-defined data type
- ◆ It is a combination of a number of previous declared types
- ◆ Usually appears near the start of a program

```
typedef struct
{
    double real;
    double imag;
} Complex; /* types usually capitalised */

Complex c1, c2;
```

Structures (2)

- The individual elements of the structure are accessed as follows:

```
double x, y;
x = c1.real - c2.imag;
y = c1.imag + c2.real;
```
- You can define a pointer to a structure in the usual way
 - `complex *c_ptr;`
- Referencing the elements of a structure when using a pointer is achieved thus:
 - `c_ptr->real;`which is equivalent to
 - `(*c_ptr).real;`...but much easier to use!
- Passing pointers to structures to functions is a good way of passing data to and fro
 - Careful of big structures though!

Exercise: Structure1

```
#include <stdio.h>

int main(void)
{
    Struct
    {
        char initial;    /* last name initial    */
        int age;         /* child's age         */
        int grade;       /* child's grade in school */
    } boy, girl;

    boy.initial = 'R';   boy.age = 15;   boy.grade = 75;

    girl.age = boy.age - 1; girl.grade = 82; girl.initial = 'H';

    printf("%c is %d years old and got a grade of %d\n",
           girl.initial, girl.age, girl.grade);
    printf("%c is %d years old and got a grade of %d\n",
           boy.initial, boy.age, boy.grade);
}
```

Expressions and Statements

- ◆ Arithmetic expressions in C look like F77

```
a = 1.0+(b-c)*d/4.0;    /* Note decimal points for floats.*/
pi = 3.141592654;      /* All statements end with a semicolon. */
area = pi*radius*radius;
```

- ◆ Functions which return values can be used in assignments

```
b = myfunc(a); /* The function myfunc() is defined elsewhere */
x = pow(x,y);
```

◆ Functions can also be used without assignments

```
do_stuff();           /* Function do_stuff() takes no arguments */
printf("x = %f\n",x); /* printf(..) is a standard C library function */
```

Operators (1)

◆ Arithmetic operators

- = assignment
- + addition
- - subtraction
- * multiplication
- / division
- % modulo
- ++ increment
- -- decrement

◆ Logical operators

- < less than
- <= less than or equal to
- > greater than
- >= greater than or equal to
- == equal to
- != not equal to

Operators (2)

◆ There are some shortcuts in C

- `i++`; is the same as `i=i+1`;
- `i++2`; is the same as `i=i+2`;
- Similarly for `--` (`**` and `//` do NOT exist)

- `a +=b`; is the same as `a = a+b`;
- Similarly for `-=` `*=` and `/=`

Control of Flow (1)

◆ if statements

```
if (logical-expression)
{statements}
else if (logical-expression)
statement;
else
{statements}
```

Note

A single statement can be used or multiple statements enclosed in a {} block.

```
if (q != 1)
{a = 0; b = 1;}
```

```
if (x < 0.)
y = x/50.;
else
{y = x/25.; x=-x;}
```

```
IF (X.LT.0.) THEN
Y = X/50.
ELSE
Y = X/25.
X=-X
ENDIF
```

Control of Flow (2)

◆ for loops

```
for (begin ; end ; increment)
{statements}
```

where:

begin; expression which is executed at beginning of loop

end; logical expression which tests for loop termination

increment; expression which is executed at the end of each loop iteration (usually incrementing a counter)

```
/* Print integers 1-10 and
their squares */
```

```
int i, j, n = 10;
for (i = 1 ; i <= n ; i++)
{
j = i*i;
printf("%d %d\n",i,j);
}
```

C Equivalent FORTRAN code

```
INTEGER I,J, N
N = 10
DO I = 1,10
J = I*I
WRITE (*,*) I,J
ENDDO
```

Exercise: Control

- ◆ Write a C program to step through the first 10 integers
- ◆ If the integer is a multiple of 3 then print out the number itself
- ◆ If the integer is a multiple of 4 then print out the number divided by one less than itself (in floating arithmetic)
- ◆ Otherwise add the number to a running total which should be output at the end

File Handling (1)

- ◆ `printf` writes formatted data to the console/screen
- ◆ `fprintf` writes to a file instead
- ◆ `scanf` and `fscanf` are similar functions for reading files

```
#include <stdio.h>
FILE *iofile;
iofile = fopen("test.dat", "w");
fprintf(iofile, "Hello, world\n");
fclose(iofile);
```

```
printf("%d\n", i);
BUT
scanf("%d", &i);
```


Exercise: Write

- ◆ Modify your control program to write the data to an output file called `control.dat`
- ◆ Save this as `write.c` in the usual way

The C Preprocessor (1)

- ◆ Commands preceded by `#` are passed through the C preprocessor (ie before compilation)
 - Header file inclusion
 - Macro definitions
- ◆ File inclusion using the directive `#include`
 - `#include <stdio.h>`
 - `#include "udf.h"`
 - `#include "mystuff.h"`
 - The files named in quotes must reside in your current directory (except for `udf.h` which is read automatically by the solver as noted earlier)

The C Preprocessor (2)

- ◆ Macro substitutions using `#define` name replacement
 - `#define RADIUS 1.2345`
 - `#define DIAM (3.14159*RADIUS)`
- ◆ The preprocessor simply substitutes the characters of name with those of replacement

The C Preprocessor (3)

- Macro substitutions can be made more like simple functions:
 - `#define SQR(A)((A)*(A))`
 - `#define DOT_PROD(A,B)(A[0]*B[0]+A[1]*B[1]\`
`+A[2]*B[2])`
- `SQR(A)` & `DOT_PROD(A,B)` are replaced by everything after the first closing “)”.
- The pattern `A` can be any expression. Note that it is in brackets `(A)` on the definition side of `SQR(A)`.
- This avoids errors when `A` is a complex mathematical expression.
- Note also that there doesn't have to be a space after the first closing “)”.
- The “\” is a continuation character used to split long `#define` lines onto multiple lines.

Exploring C Further

- Some topics not discussed here
 - while and do-while control statements
 - unions
 - recursion
 - many details!
- For more information on C programming, you may consult any general text (there are many available)

A very good set of books are published by O'Reilly, (www.oreilly.com) in particular:

Practical C Programming, 3rd Ed.
by Steve Oualline
O'Reilly, 1997

For the more dedicated, the book by the originators of C can be useful:

The C Programming Language, 2nd Ed.
by Brian Kernighan and Dennis Ritchie
Prentice-Hall, 1988